TEM0007 Test Board

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Overview

Refer to https://tem.avnet.com/tem0007-info for the current online version of this manual and other available documentation.

Key Features

- Libero SoC v2023.1
- SoftConsole v2022.2-RISC-V-747
- PolarfireSoC MSS Configurator v2023.1
- HSS (Hardware System Service) v2023.02
- Microchip polarfire SoC BSP v2022.11
- FPExpress v2023.1
- Linux distribution BSP: "Yocto Kirkstone"
- UART
- ETH
- USB
- I2C
- QSPI flash
- LPDDR4 memory

Revision History

Date	Libero SoC	Project Built	Authors	Description
2024-04-17	v2023.1	TEM0007-test_board_noprebuilt-libero_23.1-20240417101518.zip TEM0007-test_board-libero_23.1-20240417101518.zip	Mohsen Chamanbaz	• Release for more variants • The design is matched to new carrier board TEB2000.
2023-11-13	v2023.1	TEM0007-test_board_noprebuilt-libero_23.1-20231113135744.zip TEM0007-test_board-libero_23.1-20231113135744.zip	Mohsen Chamanbaz	• Clock frequency of LPDDR4 reduced to 500MHz. • USB and ethernet phys will be reset while booting.
2023-09-07	v2023.1	TEM0007-test_board_noprebuilt-libero_23.1-20230907135657.zip TEM0007-test_board-libero_23.1-20230907135657.zip	Mohsen Chamanbaz	• initial release

Design Revision History

Release Notes and Know Issues

Issues	Description	Workaround	To be fixed version
No known issues	---	---	---

Known Issues

Requirements

Software

Software	Version	Note
Libero SoC	v2023.1	needed for generating / viewing / modifying the hardware design
FPExpress	v2023.1	needed. Included within Libero SoC installation or as a standalone application .
SoftConsole	v2022.2	needed for generating / viewing / modifying the software design
PolarfireSoC MSS Configurator	v2023.1	needed for configuration of MSS
Linux distribution "Yocto"	Kirkstone	needed

Software

Additional software requirement

Requirement	Version	Note
Hart Software Services	v2023.02	needed
Microchip PolarFire SoC Yocto BSP (meta-polarfire-soc-yocto-bsp)	v2022.11	needed

Additional Software Requirement

Hardware

Complete List is available on *<project folder>/board_files/*_board_files.csv*

Design supports following modules:

Module Model	Board Part Short Name	Yocto Machine Name	PCB Revision	DDR Support	QSPI Flash	EMMC	Others	Notes
TEM0007-01-S002	25_1E0_ES_1GB	tem0007	REV01	1GB	64MB	----	----	----
TEM0007-01-CHE11-A*	250_1E_1GB	tem0007	REV01	1GB	64MB	----	----	----

TEM0007-01-CAA11-A	025_1E_1GB	tem0007	REV01	1GB	64MB	----	----	----
TEM0007-01-CAD11-A	025_1I_1GB	tem0007	REV01	1GB	64MB	----	----	----
TEM0007-01-CBD11-A	095_1I_1GB	tem0007	REV01	1GB	64MB	----	----	----

*used as reference

Hardware Modules

The Design requires one of the following carriers:

Carrier Model	PCB Revision Support	Notes
~~Modified TE0703~~	----	~~As carrier board. This board must be modified. For more information see Modified TE0703 for Microchip Getting Started~~
TEB2000*	REV01	The carrier board for TEM0007. For more information refer to TEB2000 Getting Started

*used as reference

Hardware Carrier

Additional hardware requirements:

Additional Hardware	Quantity	Notes
~~TE0790 XMOD~~	~~1~~	~~For HSS console~~
Mini USB cable for JTAG/UART	2	Check Carrier Board and Programmer for correct type
RJ45 Ethernet cable	1	
SD card	1	At least 8GB
USB Stick	1	Optional

Additional Hardware

Content

For further insight into the structure of a Trenz Reference Design Download and usage of its content in general , please follow the link Project Delivery - Microchip devices

Design Sources

Type	Location	Notes
Folder name	Path inside the Trenz Reference Download Archive	---
Libero	<project folder>/libero_source	Hardware Design Project , will be generated by TE Scripts

	<project folder>/libero_<Board Part Short Name>	Source files for specific assembly variants
SoftConsole	<project folder> /softconsole_source	Software Design / Boot Code / Bootloader / Application Software
Yocto	<project folder>/os/yocto	Linux distribution. Trenz electronic yocto BSP files for TEM0007
	<project folder>/prebuilt	Compiled binaries to program Hard and Soft -ware Designs
	<project folder>scripts	TE Scripts folder
*.cmd	<project folder>	Starting scripts for the most imported TE Scripts

Design sources

Prebuilt

File	File-Extension	Description
Libero Project File	*.prjx	Project file
FlashPro Express Job	*.job	The exported job file contains the data contents to be programmed into PolarFire FPGA and external SPI Flash. This job file is used in the FlashPro Express software to program both device and external SPI Flash.
Constraint File	*.pdc	IO constraint file
Timing Constraint File	*.sdc	Timing constraint file
Configuration File	*.cfg	Polarfire MSS configuration file is prepared in Polarfire MSS Configurator software. The Polarfire MSS Configuration software will export the *.xml , *.cxf files after that.
Components in Block Design	*.cxf	Exported file of Polarfire MSS Configuration software for importing in Libero software
xml file	*.xml	Exported file of Polarfire MSS Configuration software for importing in SoftConsole software
Software Application File	*.hex	Generated hex file by SoftConsole software to program on eNVM memory of Polarfire SoC
Software-Application-File	*.elf	Software application generated by SoftConsole software
Libero Application File	*.ppd / *dat	Bitstream files

Device Tree	*.dtb	Device tree blob
CONF-File	*.conf	Boot configuration file
Yocto linux image	*.wic	This File can be flashed via bmaptool command in host linux or other tools same as Win 32DiskImager or balenaEtcher on the SD card.
Yocto linux image	*.img	Linux image for SD card

Prebuilt files (only on ZIP with prebult content)

Download

Reference Design is only usable with the specified Libero version. Do never use different versions of Libero software for the same project.

Reference design is available on:

- TEM0007 "Test Board" Reference Design

Design Flow

Trenz Electronic provides a TCL project generation based on Microchip's Design Flow where possible.

See also:

- Project Delivery - Microchip devices

Libero SoC

Reference Design is available with and without prebuilt files. It's recommended to use TE prebuilt files for first launch.

The Libero SoC Hardware Design Project for this board is delivered as a TCL script which utilizes the Libero SoC Command API .

The script Libero SoC Project will be generated into the folder "<project folder> / libero_<Variant short name>".

- Run the script "Generate_TEM0007_Hardware-Design_in_Libero_SoC_v2023.1.cmd" and follow instructions on the console :
  - The script searches for a suitable Libero SoC installation at the beginning and lists them plus some other option to manually guide the script to the Libero SoC installation of your liking .
  - Further will the script offer options to chose from :
    - Upgrade all Libero SoC General Soft Cores
    - Select your Trenz Board Subversion / Assembly Variant from a list
    - Select the set of Soft Cores to be used during project generation. The set of soft cores versions used during development or the newest available versions and if possible this selection is possible , download them or use a copy from the Trenz Download
    - When necessary , to resolve a Folder Overwrite Conflict
    - Chose your prefered Hardware Description Language (VHDL / Verilog)
- After the project generation , the script continues with the following options :
  - Compile the bitstream of the project and obtain the Programming Files
  - Open the project for use

Project generation script console messages

```
    E:\Microchip_svn\23.1\designs\TEM0007\test_board\scripts\
Generate_TEM0007_Hardware-Design_in_Libero_SoC_v2023.1

--------------- Start : design_subversion_setup.tcl
---------------

###   Autostart via System Path Variable "acttclsh"   ### -
Probing for acttclsh.exe
"where acttclsh"
INFORMATION: Es konnten keine Dateien mit dem angegebenen
Muster gefunden werden.

###   Autostart via System Path Variable "tclsh"   ### -
Probing for tclsh.exe
"where tclsh"
INFORMATION: Es konnten keine Dateien mit dem angegebenen
Muster gefunden werden.

###   Autostart searching for default Libero SoC
installation   ### - Searching for acttclsh.exe
List of Libero_SoC installations in c:\Microchip\ and their
TCL Shell(s) :
Libero_SoC_v2023.1
    c:\Microchip\Libero_SoC_v2023.1\Designer\bin\acttclsh.exe

# Autostart via Libero_SoC TCL Shell # - Executing script
    Using TCL Shell  c:\Microchip\Libero_SoC_v2023.
1\Designer\bin\acttclsh.exe

Processing script parameters :
  Setting dict key:windowWidth value:118 pair
  Console window has width : 118
  Parameter path not an argument to this script : key "path"
not known in dictionary

--------------------   TEM0007 test_design
--------------------
TCL Version : 8.6


This script generates the Hardware Design for the Trenz
Electronic module series TEM0007.
        The Hardware Design itself is a Microchip Libero SoC
Design Suite project.

This script requires a Libero SoC installation equal or later
than :
        Libero SoC Version   2023.1


        [When the built stops with the error message :
         Error: Cannot find Spirit core configuration file
for vendor:.. library:.. name:.. version:...
         Error: The command 'create_and_configure_core'
failed.

         Upgrading the Libero SoC Soft Core Catalog can help .
         To do so , use the script option to upgrade the
```

```
cores later in this script .

         Manually this is done via :
         Open Libero and go to the Soft Core Catalog via
"View > Windows > Catalog"
         and press the button "Download them now!" .]


Found Libero SoC installations in default folder :
  C:/Microchip/Libero_SoC_v2023.1
  C:/Microsemi/Libero_SoC_v2021.2
  C:/Microsemi/Libero_SoC_v12.4

### Select from the following options which Libero SoC
version should be used
    to build the design :

    Option 0 : C:/Microchip/Libero_SoC_v2023.1/Designer/bin
/libero.exe
    Option 1 : Enter path to your Microchip or Libero SoC
installations folder
               The script selects automatically the Libero exe
    Option 2 : Enter the full path to your Libero SoC exe
    Option 3 : Exit the script
    Selection : (0 to 3) 0

  Using Libero SoC @ : C:/Microchip/Libero_SoC_v2023.1
/Designer/bin/libero.exe


### Do you wish to update the Libero SoC Soft Cores ?
     (Yes = y/t/1 or No = n/f/0) : 1
  Updating soft cores started

Console Mode = Downloading Microchip:SolutionCore:YCbCrtoRGB:
4.6.0...
OK
Info:  Core 'Microchip:SolutionCore:YCbCrtoRGB:4.6.0' was
successfully downloaded.
Downloading Microsemi:MiV:MIV_RV32:3.1.200...
OK

### Hardware Designs are available for these variants :
    ID   :  PRODID               FAMILY           DEVICE
PACKAGE   SPEED   TEMP   SHORTNAME     FLASH_SIZE
             DDR_SIZE   PCB_REV   NOTES

       1 :  TEM0007-01-S002      "PolarfireSoC"   MPFS250T_ES
FCVG484   STD     EXT    25_1E0_ES_1GB NA
             1GB        REV01     "produced prototyp"
       2 :  TEM0007-01-CHE11-A   "PolarfireSoC"   MPFS250T
FCVG484   STD     EXT    250_1E_1GB    NA
             1GB        REV01     "produced"
       3 :  TEM0007-01-CAA11-A   "PolarfireSoC"   MPFS025T
FCVG484   STD     EXT    025_1E_1GB    NA
             1GB        REV01     "currently factory order
5555"
       4 :  TEM0007-01-CAD11-A   "PolarfireSoC"   MPFS025T
FCVG484   -1      IND    025_1I_1GB    NA
             1GB        REV01     "currently ERP only"
       5 :  TEM0007-01-CBD11-A   "PolarfireSoC"   MPFS095T
```

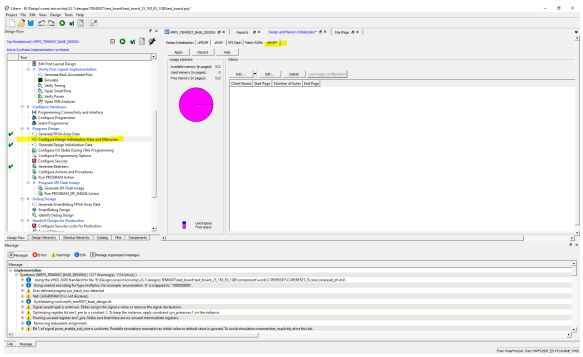
```
FCVG484   -1      IND    095_1I_1GB    NA
            1GB        REV01     "currently factory order
5555"
       6 :  Exit script

    Enter ID number of your board (1 to 6) : 1


### Which Soft Core Versions should be used to generate the
Hardware Design ?
    (The design can be generated with local sources ,
     when a Libero SoC version with the same major version is
used)

    Option 0 : Download the newest soft core versions
    Option 1 : Download the soft cores versions , for which
the Hardware Design was verified
    Option 2 : Use a local copy of the soft cores sources ,
which the Hardware Design was verified for
    Option 3 : Exit script
    Selection : (0 to 3) 1


### Folder overwrite protection .
    Checking for existing Libero SoC project folder named
"libero_25_1E0_ES_1GB" :
    Found existing Libero SoC project folder
"libero_25_1E0_ES_1GB"

    Select how to proceed :
    Option 0 : Overwrite this Libero SoC project folder
    Option 1 : Enter new Libero SoC project folder name
    Option 2 : Exit script
    Selection : (0 to 2) 0


### Which Hardware Description Language do you prefer :
    VHDL or Verilog ?
    Option 0 : VHDL
    Option 1 : Verilog
    Option 2 : Exit script
    Selection : (0 to 2) 0


### Determine expected Libero SoC Project path lengths :
    Expected maximum Libero SoC Project path length :
  root  + project name  + relatvive path  =  path length
     48   +      21  +     135   =     204

  The root path length is well below the Libero SoC Path
Length Limit of 250 chars .
  The Hardware Designs Build / Synthesis or Bitstream
generation should succeeded .


### Building the hardware design started at 17:17:38 , this
will take some minutes .
        [In rare cases, this console may not advance from
here on .
         Visible through a not blinking cursor. Wait some
minutes ,
```

```
         focus the console and press space, the script will
continue .]


### Checking the results via log evaluation :
  Hardware design generation was successfull  The projects
path is :
E:/Microchip_svn/23.1/designs/TEM0007/test_board
/libero_25_1E0_ES_1GB

  The build log "libero_25_1E0_ES_1GB_build_2024.02.19_171738.
log" was saved to :
E:/Microchip_svn/23.1/designs/TEM0007/test_board/log


### Hardware Design Compilation and Bitstream Generation :
        Do you want the these files to be build and exported ?
        Selection (Yes = y/t/1 or No = n/f/0) : 1


  Generating folders for prebuilt files
  Folder bitstream already exists and will be overwritten
  Folder flashpro already exists and will be overwritten


### Executing the prebuilt started at 17:22:24 , this will
take some minutes .


### Checking the results via log evaluation :
Generation and export of Prebuilt Files was successfull

The files have been exported to the subfolders
bitstream and flashpro inside :
E:/Microchip_svn/23.1/designs/TEM0007/test_board/prebuilt
/hardware/25_1E0_ES_1GB

The prebuilt log "libero_25_1E0_ES_1GB_prebuilt_2024.02.19
_171738.log" was saved to :
E:/Microchip_svn/23.1/designs/TEM0007/test_board/log


### Open the generated Libero Soc TEM0007 test_design ?
Selection (Yes = y/t/1 or No = n/f/0) : 1


Please press any key . . .
```

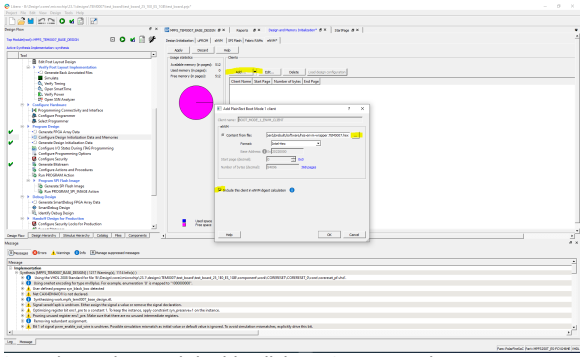
- Now the generated and exported files existing in prebuilt folder are without HSS generated hex /elf file. If the hex file is attached to job file it will not be necessary to program HSS generated hex file on eNVM memory. To attach the hex file to job file execute the following instructions (optional).

  > ⚠ In test board reference zip file the job files in prebuilt folder consist of HSS generated hex file. The following instruction are only to know , how the final job file is prepared and regenerated.

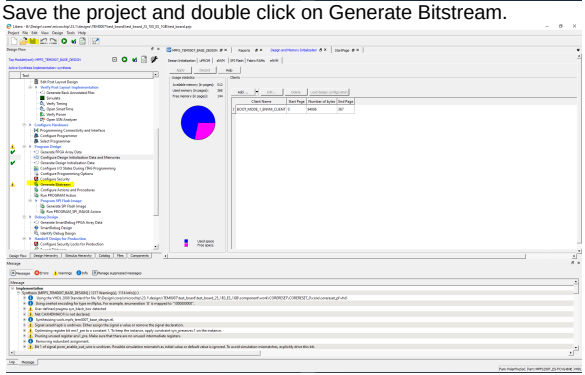
- After generating bitstream file double click on "Configure Design Initialization Data and Memories" in Design Flow now.



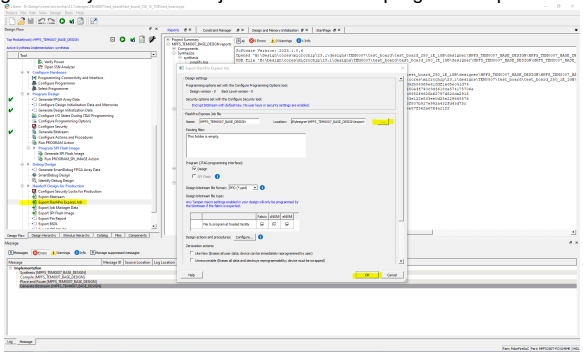
- Click on eNVM and after that on Add and click on Add Boot Mode 1 Client.
- Enter the path of generated *.hex *File by* SoftConsole software (HSS) or the path of saved *.hex file in prebuilt folder (for example "...\test_board\prebuilt\hardware\250_1E_1GB"and click on OK.



- Save the project and double click on Generate Bitstream.



- Double click on "Export Flashpro ExpressJob" and enter the desired path for *.job file to generate *.job File. The* *.job will be used to program the polarfire soc in FPExpress software.



Launch

Hardware Setup

- Connect the TEB2000 carrier board via its J4 mini USB connector to the PC. (For Linux console)
- Connect the TEB2000 carrier board via its J21 mini USB connector to the PC. (For HSS console)
- Connect the 5V power supply to 5V input voltage connector J13.
- Connect the RJ45 network cable to the ethernet interface J14.
- Connect the USB stick to the USB stick socket J12.
- For more information see TEB2000 Getting Started

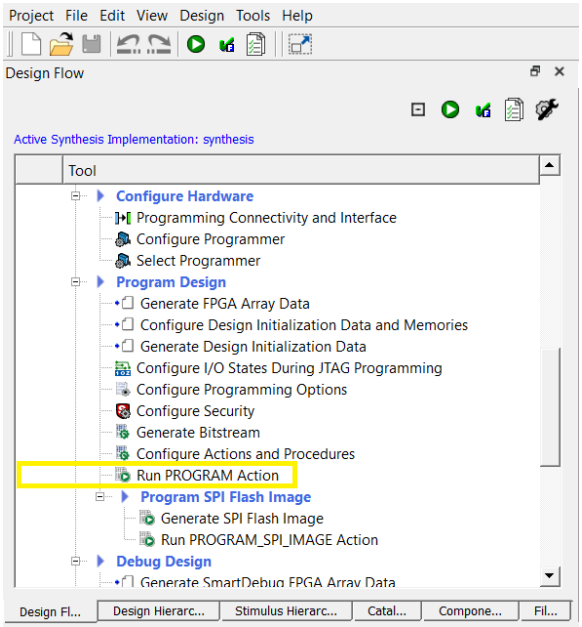
Programming Bitstream

> ⚠ Check module and carrier TRMs for proper HW configuration before you try any design.

There is two ways to program bitstream file on FPGA. The Bitstream can be programmed into the FPGA / SOC by Libero SoC or Flash Pro Express :

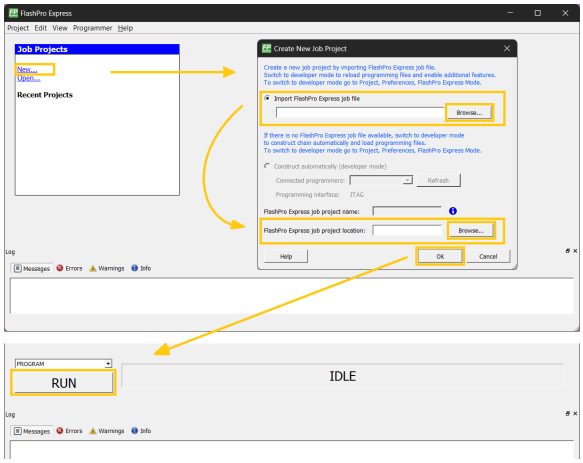
Using Libero SoC

- Prepare the hardware see Hardware Setup
- Double click onto "Run PROGRAM Action" to program the Polarfire SoC.



Using FPExpress software

- Prepare the hardware see Hardware Setup
- Click on NEW... to open the "Creat New Job Project" dialog
- Clicking onto the upper Browse... button to specify the Programming Job File location
- Clicking onto the lower Browse... button to specify the location of where to store the FlashPro Express Job Project which will be created .The Job Project name automatically uses the programming job name and cannot be changed .
- Click OK and a new Job Project will be created and opened for production programming
- Click on RUN to start the programming of a board



Programming eNVM

The eNVM is a user non-volatile flash memory that can be programmed independently. There is two methods to program eNVM:

Programming eNVM in SoftConsole

To program HSS *.hex file on FPGA:

- Prepare the hardware see Hardware Setup
- Open SoftConsole software as administrator, if it is not done yet.
- Select correct directory as workspace directory and import hart-software-services source code.
- Right click on the hart-software-services and click on Build Project, if it is not done yet. For more information see Hart Software Services (HSS)
- Click on Run > External Tools > Polarfire SoC program non-secure boot-mode 1

Programming eNVM in Flashpro Express

The HSS generated hex file can be attached to bitstream file. For more information see Design Flow

To program the eNVM in Flashpro Express see Using FlashPro Express

SD-Boot mode

This module supports SD card boot and JTAG boot mode. The selection between them will be done in HSS, so there is no need to select the boot mode via Dip Switches .

Prepare SD card as follows for SD card boot mode:

1. Extract SD_Card.zip file
2. Now there is a image file (SD_Card.img)
3. Alternative SD card can be written via win32diskimager or balenaEtcher softwares in Windows OS.
4. In the case of writing image file in linux there are two commands to write image file on the SD card after mounting SD card in the host linux same as WSL:
    a.
```
bmaptool copy --nobmap <Path of image file *.img>  /dev/sdX
```
        i. After mounting the SD card in linux the name of SD card recognized via "lsblk" command. For example SD card name can be sda or sdb.
    b.
```
dd if=<Path of image file *.img> of=/dev/sdX
```
        i. After mounting the SD card in linux the name of SD card recognized via lsblk command. For example SD card name can be sda or sdb.

JTAG

Not used on this example.

Usage

- Prepare HW like described on section Hardware Setup
- Power on PCB

UART

1. Open two serial console for HSS and Linux console (e.g. PuTTY)
    a. Select COM Port of linux console (UART1)

    > Win OS: see device manager
    >
    > Linux OS: see dmesg | grep tty (UART is *USB1)

    b. Select COM port of HSS console (UART0)
    c. Speed for both consoles : 115200
2. Press reset button
3. Console output depends on used software project, see Application
4. HSS console (UART0):
    a. This console can be monitored by user , to know some additional information same as SD card status (If SD card by booting is detected or not) , U54 cores status or memory size , ...

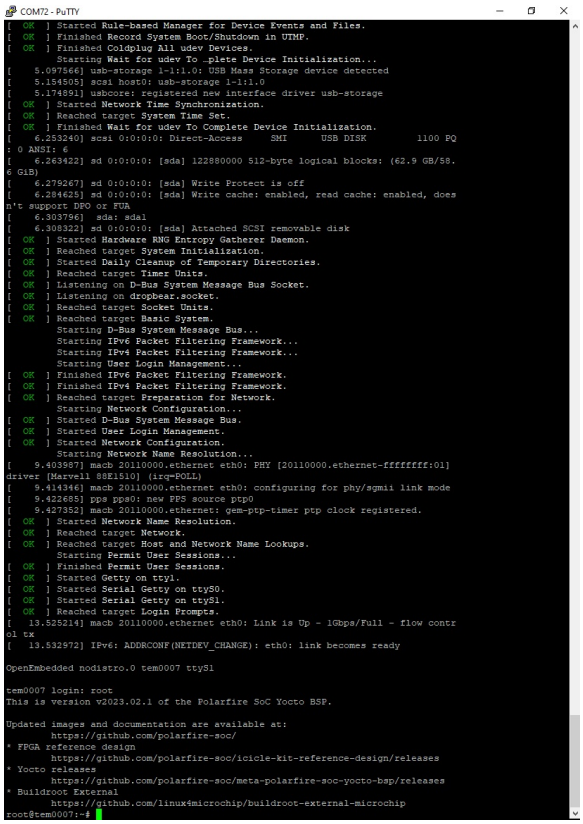
5. Linux Console (UART1):
    a. Login data:

> Note: Wait until Linux boot finished

```
tem0007 login: root
```

    b. You can use Linux shell now.

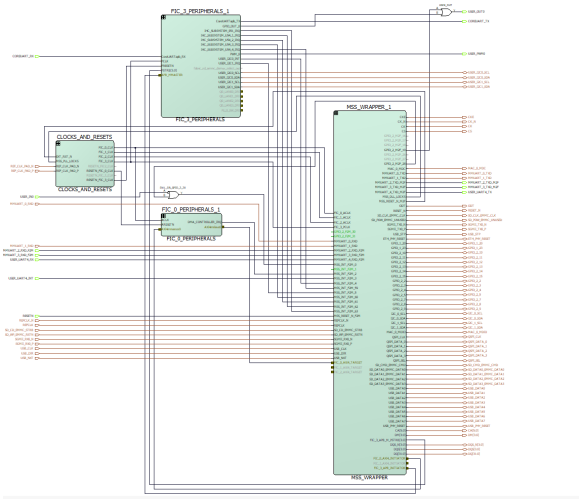
```
i2cdetect -l        (check I2C Bus)
ifconfig -a         (ETH0 check)
lsusb               (USB check)
```



System Design - Libero

Block Design

The Block Design of a board variant or revision may differ slightly depending on the assembly variant.



Block Design

HPS Interfaces

Activated interfaces:

Type	Note
DDR	--
EMAC0	--
GPIO1	--
GPIO2	--
I2C0	--
I2C1	--
SPI0	--
QSPI	--
SDMMC	--
UART0	--
UART1	--
USB	--

Constraints

TEM0007_Bank_Voltage.pdc

```
set_iobank -bank_name Bank0  \
    -vcci 1.80               \
    -fixed true             \
    -update_iostd true

set_iobank -bank_name Bank1  \
    -vcci 3.30               \
    -fixed true             \
    -update_iostd true

set_iobank -bank_name Bank4  \
    -vcci 3.30               \
    -fixed true             \
    -update_iostd true
```

TEM0007_Clock.pdc

```
set_io -port_name REF_CLK_PAD_P  \
    -pin_name J19                \
    -DIRECTION INPUT

set_io -port_name REF_CLK_PAD_N  \
    -pin_name J20                \
    -DIRECTION INPUT
```

TEM0007_GPIOs.pdc

```
set_io -port_name GPIO_2_2  \
    -pin_name D9              \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_3  \
    -pin_name D6              \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_4  \
    -pin_name C6              \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_7  \
    -pin_name B5              \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_8  \
    -pin_name C5              \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_9  \
    -pin_name C4              \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_11  \
    -pin_name F16             \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_12  \
    -pin_name D14             \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_13  \
    -pin_name E14             \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT

set_io -port_name GPIO_2_14  \
    -pin_name B4              \
    -fixed true               \
    -io_std LVCMOS33          \
    -DIRECTION INOUT
```

TEM0007_MAC.pdc

```
set_io -port_name MAC_0_MDC \
    -pin_name H6 \
    -fixed true \
    -DIRECTION OUTPUT \
    -io_std LVCMOS33

set_io -port_name MAC_0_MDIO \
    -pin_name J3 \
    -fixed true \
    -DIRECTION INOUT \
    -io_std LVCMOS33
```

TEM0007_MMUART0.pdc

```
 set_io -port_name MMUART_0_TXD \
    -pin_name C2 \
    -fixed true \
    -DIRECTION OUTPUT \
    -io_std LVCMOS33

set_io -port_name MMUART_0_RXD \
    -pin_name D3 \
    -fixed true \
    -DIRECTION INPUT \
    -io_std LVCMOS33
```

TEM0007_MMUART1.pdc

```
set_io -port_name MMUART_1_TXD \
    -pin_name H5 \
    -fixed true \
    -DIRECTION OUTPUT \
    -io_std LVCMOS33

set_io -port_name MMUART_1_RXD \
    -pin_name H2 \
    -fixed true \
    -DIRECTION INPUT \
    -io_std LVCMOS33
```

TEM0007_Peripheral.pdc

```
set_io -port_name USER_PWM0    \
    -pin_name D7    \
    -fixed true    \
    -io_std LVCMOS33  \
    -RES_PULL Down \
    -DIRECTION OUTPUT

set_io -port_name USER_IN0 \
    -pin_name V19 \
    -fixed true \
    -DIRECTION INPUT

set_io -port_name USER_OUT0 \
    -pin_name AB19 \
    -fixed true \
    -DIRECTION OUTPUT

# JM2-Pin73/ JB2-Pin74 / B13_L16_N (Suitable for modified TE0703)
#set_io -port_name RESETN  \
    -pin_name H13         \
    -fixed true           \
    -io_std LVTTL         \
    -CLAMP_DIODE OFF      \
    -RES_PULL Up          \
    -DIRECTION INPUT

# JM2-Pin55 TEM0007 / JB2-Pin56 (SRST) TEB2000 / B13_L9_P
set_io -port_name RESETN  \
    -pin_name E15         \
    -fixed true           \
    -io_std LVTTL         \
    -CLAMP_DIODE OFF      \
    -RES_PULL Up          \
    -DIRECTION INPUT
```

TEM0007_QSPI.pdc

```
set_io -port_name QSPI_CLK  \
    -pin_name C10           \
    -fixed true             \
    -io_std LVCMOS33        \
    -DIRECTION INOUT

set_io -port_name QSPI_DATA_0  \
    -pin_name D13              \
    -fixed true                \
    -io_std LVCMOS33           \
    -DIRECTION INOUT

set_io -port_name QSPI_DATA_1  \
    -pin_name B12              \
    -fixed true                \
    -io_std LVCMOS33           \
    -DIRECTION INOUT

set_io -port_name QSPI_DATA_2  \
    -pin_name C9               \
    -fixed true                \
    -io_std LVCMOS33           \
    -DIRECTION INOUT

set_io -port_name QSPI_DATA_3  \
    -pin_name C12              \
    -fixed true                \
    -io_std LVCMOS33           \
    -DIRECTION INOUT

set_io -port_name QSPI_SEL  \
    -pin_name A13           \
    -fixed true             \
    -io_std LVCMOS33        \
    -DIRECTION INOUT
```

MPFS_TEM0007_BASE_DESIGN_derived_constraints.sdc

```
create_generated_clock -name {CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK
/PF_CCC_C0_0/pll_inst_0/OUT0} -multiply_by 5 -source [ get_pins {
CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK/PF_CCC_C0_0/pll_inst_0/REF_CLK_0 }
] -phase 0 [ get_pins { CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK/PF_CCC_C0_0
/pll_inst_0/OUT0 } ]
create_generated_clock -name {CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK
/PF_CCC_C0_0/pll_inst_0/OUT1} -multiply_by 5 -source [ get_pins {
CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK/PF_CCC_C0_0/pll_inst_0/REF_CLK_0 }
] -phase 0 [ get_pins { CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK/PF_CCC_C0_0
/pll_inst_0/OUT1 } ]
create_generated_clock -name {CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK
/PF_CCC_C0_0/pll_inst_0/OUT2} -multiply_by 5 -source [ get_pins {
CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK/PF_CCC_C0_0/pll_inst_0/REF_CLK_0 }
] -phase 0 [ get_pins { CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK/PF_CCC_C0_0
/pll_inst_0/OUT2 } ]
create_generated_clock -name {CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK
/PF_CCC_C0_0/pll_inst_0/OUT3} -multiply_by 2 -source [ get_pins {
CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK/PF_CCC_C0_0/pll_inst_0/REF_CLK_0 }
] -phase 0 [ get_pins { CLOCKS_AND_RESETS_inst_0/CCC_FIC_x_CLK/PF_CCC_C0_0
/pll_inst_0/OUT3 } ]
create_generated_clock -name {CLOCKS_AND_RESETS_inst_0/PF_CLK_DIV_C1_0
/PF_CLK_DIV_C1_0/I_CD/Y_DIV} -edges {1 7 11} -source [ get_pins {
CLOCKS_AND_RESETS_inst_0/PF_CLK_DIV_C1_0/PF_CLK_DIV_C1_0/I_CD/A } ] [
get_pins { CLOCKS_AND_RESETS_inst_0/PF_CLK_DIV_C1_0/PF_CLK_DIV_C1_0/I_CD
/Y_DIV } ]
set_false_path -through [ get_nets { FIC_0_PERIPHERALS_1
/DMA_INITIATOR_inst_0/ARESETN* } ]
set_false_path -through [ get_nets { FIC_0_PERIPHERALS_1
/FIC0_INITIATOR_inst_0/ARESETN* } ]
```

Software Design - SoftConsole

Application

Template location: <*project folder*>/*softconsole_source/*

Hart Software Services (HSS)

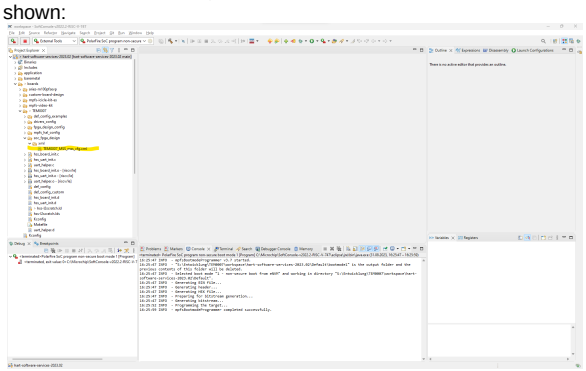
Hart Software Services (HSS) code on PolarFire SoC, is comprised of two portions:

- A superloop monitor running on the E51 minion processor, which receives requests from the individual U54 application processors to perform certain services on their behalf.
- A Machine-Mode software interrupt trap handler, which allows the E51 to send messages to the U54s, and request them to perform certain functions for it related to rebooting a U54.

The HSS performs boot and system monitoring functions for PolarFire SoC. The HSS is compressed (DEFLATE) and stored in eNVM. On power-up, a small decompressor wrapper inflates the HSS from eNVM flash to L2-Scratchpad memory and starts the HSS.

Creating HSS workspace in SoftConsole

1. Download the test board design zip file in the following path : TEM0007 "Test Board" Reference Design
2. Unzip the test board zip file
3. Copy the HSS folder (hart-software-services-<HSS version>) from softconsole_source folder in the SoftConsole workspace folder
4. Open SoftConsole software as administrator
5. Select correct directory as workspace directory. The workspace folder must consist of **hart-software-services-<HSS version>** folder. The **hart-software-services-<HSS version>** project can be imported in the workspace as an Existing project.
6. Left click on **board** folder
7. There is created already a subfolder for TEM0007 module and HSS is ready to be compiled as shown:



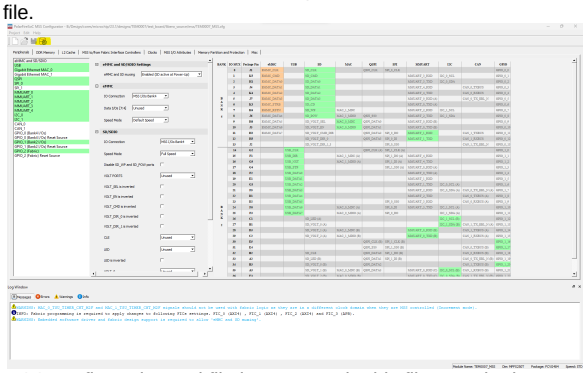
8. Right click on hart-software-services-<HSS version> and click on Build project to compile it.
9. It is ready to program created hex file on the Polarfire SoC. See Programming eNVM

Note that HSS can be changed for every TEM0007 variant. Therefore the hex file for every variant is created and saved in the following path of test design folder separately: **(<project folder>/prebuilt /soctware/<short name of the module variant>)**

Creating XML file in PolarfireSoC MSS Configurator Software

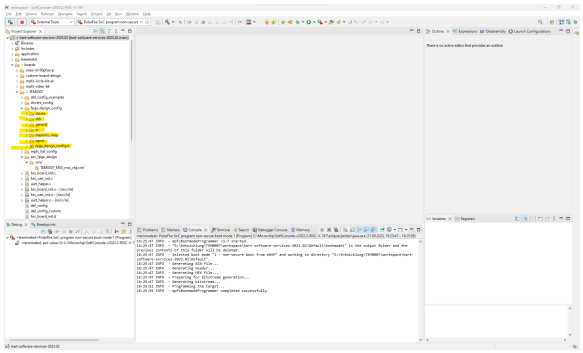
To create HSS file for a desired module variant the saved MSS configuration xml file in "**<softconsole workspace folder>/ hart-software-services-<HSS version>/board/TEM0007/soc_fpgs_design/xml/**" must be matched for its related xml file. To do it:

1. Open the PolarfireSoC MSS Configurator software.
2. Click on ProjectOpen
3. Select the generated **TEM0007_MSS.cfg** file that is saved in the "**<project folder>/prebuilt /mss/<short name of the module variant>**" folder.
4. Click on Generate icon. It will be opened a window to enter the desired path for generated xml file.



5. MSS configuration xml file is generated. This file must be imported in SoftConsole software. To import this file copy the generated MSS configuration xml file and replace it with previous xml file in the following path : "**<softconsole workspace folder>/ hart-software-services-<HSS version>/boards/TEM0007/soc_fpga_design/xml**"
6. Right click on the project in SoftConsole software and click on Clean Project.

7. In SoftConsole software delete all configuration header files in "**<softconsole workspace folder>/ hart-software-services-<HSS version>/boards/TEM0007/fpga_design-config**" folde r.



8. Right click on the project in SoftConsole software again and click on Build Project to compile the project.
9. The new configuration header files will be generated again by the python script in "**<softconsole workspace folder>/ hart-software-services-<HSS version>/tools/polarfire-soc-configuration-generator/mpfs_configuration_generator.py** " folder. The generated hex file can be found in the "**<softconsole workspace folder>/ hart-software-services-<HSS version>/Default** " folder.
10. This new hex file must be replaced in Libero to generate new Bitstream file, if this hex file should be attached in Bitstream file. See Libero SoC
    Note that this hex file can be programmed in eNVM in SoftConsole directly. See Programming eNVM in SoftConsole

Software Design - Yocto

The host pc must be prepared for using the yocto. For more information about host pc setup for yocto and the required packets please refer to System Requirements

Trenz electronic has developed his own BSP for Microchip devices same as polarfire soc in Yocto. In the following will be explained the folders in detail.

meta-trenz-polarfire-bsp Folder	Description
recipes-apps*	Consists of start up application for executing of init.sh by booting. More application can be saved in this folder.
recipes-bsp	Consists of uboot required files same as *. bbappend files, device tree and etc.
recipes-core	Consists of *.bb file for Trenz defined image version. This file consists of required packets or files that must be installed.
recipes-kernel	Consists of kernel required files same as *. bbappend files, device tree, config files and etc.
recipes-tools	Consists of a *.bbappend file.
tools	Consists of manifest xml file to define meta data that are required.
wic	Consists of *.wks file that describes disk image properties.

*Note: In this version is not used.

In the following table exists more information about required packets and supported version.

Meta data	Supported Version	Description
meta-riscv	Kirkstone	
openembedded-core	Kirkstone	
meta-openembedded	Kirkstone	
meta-polarfire-soc-yocto-bsp	2022.11	

Trenz BSP contains of a shell script. If this shell script is executed , all required processes for making a linux image file will be executed automatically. The user needs only to write the generated image file on the SD card. To prepare the image file :

1. Create a new folder (for example TEM0007) in host linux (here Ubuntu18.04 and Ubuntu 20.04 have been tested)
2. Download the test board design as zip file (See Download) and save meta-trenz-polarefile-bsp BSP folder from "**<project folder>/os/yocto/** " folder in the created folder. (for example TEM0007)
3. Go to the created folder (for example TEM0007) that meta-trenz-polarfire-bsp is saved and execute its shell script as shown:

   ```
   . ./meta-trenz-polarfire-bsp/trenz_polarfire_setup.sh
   ```

   ***Note: The shell script must be executed in created new folder (for example TEM0007) that has bsp folder saved in it.**
4. After compiling image file *.img and its converted zip file *.zip will be saved in trenz bsp folder:
   - " <trenz BSP folder>/prebuilt/boot/yocto/SD_Card.img "
   - " <trenz BSP folder>/prebuilt/boot/yocto/SD_Card.zip "

U-Boot

File location: *<trenz BSP folder>/recipes-bsp/u-boot/*

Changes:

- CONFIG_PHY_MARVELL=y
- CONFIG_DEFAULT_DEVICE_TREE="tem0007"
- CONFIG_DEFAULT_FDT_FILE="tem0007.dtb"
- CONFIG_OF_LIST="tem0007"
- CONFIG_DM_GPIO=y
- CONFIG_CMD_GPIO=y
- CONFIG_LOG=y
- CONFIG_LOG_MAX_LEVEL=y
- CONFIG_LOG_CONSOLE=y
- CONFIG_NVMEM=y to be able to read MAC vom EEPROM
- CONFIG_DM_RTC=y

Device Tree

U-boot Device Tree

tem0007.dtsi

```
// SPDX-License-Identifier: (GPL-2.0 OR MIT)
/*
 * Copyright (C) 2020 Microchip Technology Inc.
 * Padmarao Begari <padmarao.begari@microchip.com>
 */

/ {
        aliases {
                cpu1 = &cpu1;
                cpu2 = &cpu2;
                cpu3 = &cpu3;
                cpu4 = &cpu4;
        };
};
```

tem0007.dts

```
// SPDX-License-Identifier: (GPL-2.0+ OR MIT)
/*
 * Copyright (C) 2021 Microchip Technology Inc.
 * Padmarao Begari <padmarao.begari@microchip.com>
 */

/dts-v1/;

#include "microchip-mpfs.dtsi"
#include "dt-bindings/gpio/gpio.h"

/* Clock frequency (in Hz) of the rtcclk */
#define RTCCLK_FREQ                1000000

/ {
        model = "Microchip PolarFire-SoC Icicle Kit";
        compatible = "microchip,mpfs-icicle-kit", "microchip,mpfs";

        aliases {
                serial1 = &uart1;
                ethernet0 = &mac0;
                spi0 = &qspi;
        };

        chosen {
                stdout-path = "serial1";
        };

        cpus {
                timebase-frequency = <RTCCLK_FREQ>;
        };

        ddrc_cache: memory@80000000 {
                device_type = "memory";
                reg = <0x0 0x80000000 0x0 0x40000000>;
                clocks = <&clkcfg CLK_DDRC>;
                status = "okay";
        };

    usb_phy: usb_phy {
        #phy-cells = <0>;
        compatible = "usb-nop-xceiv";
```

```
        reset-gpios = <&gpio1 17 GPIO_ACTIVE_LOW>;
        reset-names = "OTG_RST";
    };
};

&uart1 {
        status = "okay";
};

&mmc {
        status = "okay";
        bus-width = <4>;
        disable-wp;
        cap-mmc-highspeed;
        cap-sd-highspeed;
    cd-debounce-delay-ms;
        card-detect-delay = <200>;
        // mmc-ddr-1_8v;
        // mmc-hs200-1_8v;
        sd-uhs-sdr12;
        sd-uhs-sdr25;
        sd-uhs-sdr50;
        sd-uhs-sdr104;
};

&i2c1 {
        status = "okay";
    #address-cells = <1>;
        #size-cells = <0>;
        eeprom: eeprom@50 {
                compatible = "microchip,24aa025", "atmel,24c02";
        //compatible = "atmel,24c02";
                reg = <0x50>;
                #address-cells = <1>;
                #size-cells = <1>;
                eth0_addr: eth-mac-addr@FA {
                        reg = <0xFA 0x06>;
                };
        };
};

&refclk {
        clock-frequency = <125000000>;
};

&mac1 {
        status = "disabled";
};

&mac0 {
        status = "okay";
        phy-mode = "sgmii";
    nvmem-cells = <&eth0_addr>;
        nvmem-cell-names = "mac-address";
        phy-handle = <&phy0>;
        phy0: ethernet-phy@1 {
                device-type = "ethernet-phy";
                reg = <1>;
        reset-names = "ETH_RST";
        reset-gpios = <&gpio1 16 GPIO_ACTIVE_LOW>;
        };
```

```
};



&qspi {
        status = "okay";
        num-cs = <1>;
        flash0: spi-nor@0 {
                compatible = "spi-nor";
                reg = <0x0>;
                spi-tx-bus-width = <4>;
                spi-rx-bus-width = <4>;
                spi-max-frequency = <20000000>;
                spi-cpol;
                spi-cpha;
        };
};

&usb {
        status = "okay";
        dr_mode = "otg";
        // dr_mode = "host";
        phys = <&usb_phy>;
};
```

Kernel Device Tree

tem0007.dts

```
// SPDX-License-Identifier: (GPL-2.0 OR MIT)
/* Copyright (c) 2020-2021 Microchip Technology Inc */

/dts-v1/;

#include "mpfs.dtsi"

#include <dt-bindings/gpio/gpio.h>
#include <dt-bindings/phy/phy.h>

/* Clock frequency (in Hz) of the rtcclk */
#define MTIMER_FREQ                1000000

/ {
        #address-cells = <2>;
        #size-cells = <2>;


        model = "Trenz TEM0007";
        compatible = "trenz,tem0007","microchip,mpfs";

        aliases {
                ethernet0 = &mac0;
                serial0 = &mmuart0;
                serial1 = &mmuart1;
                serial2 = &mmuart2;
                serial3 = &mmuart3;
                serial4 = &mmuart4;
```

```
        };

        chosen {
                stdout-path = "serial1:115200n8";
        };

        cpus {
                timebase-frequency = <MTIMER_FREQ>;
        };



        //*******************************************************//

        ddrc_cache: memory@80000000 {
                device_type = "memory";
                reg = <0x0 0x80000000 0x0 0x40000000>;
                status = "okay";
        };

        reserved-memory {
                #address-cells = <2>;
                #size-cells = <2>;

                ranges;

                fabricbuf0ddrc: buffer@A0000000 {
                        compatible = "shared-dma-pool";
                        reg = <0x0 0xA0000000 0x0 0x2000000>;
                        no-map;
                };
        };

        udmabuf0 {
                compatible = "ikwzm,u-dma-buf";
                device-name = "udmabuf-ddr-c0";
                minor-number = <0>;
                size = <0x0 0x2000000>;
                memory-region = <&fabricbuf0ddrc>;
                sync-mode = <3>;
        };


        //*******************************************************//

        usb_phy: usb_phy {
                #phy-cells = <0>;
                compatible = "usb-nop-xceiv";
                reset-gpios = <&gpio1 17 GPIO_ACTIVE_LOW>;
                reset-names = "OTG_RST";
        };


        soc {
                dma-ranges = <0 0 0 0 0x40 0>;
        };
};

&gpio1 {
        status = "okay";
};
```

```
&gpio2 {
        interrupts = <53>, <53>, <53>, <53>,
                <53>, <53>, <53>, <53>,
                <53>, <53>, <53>, <53>,
                <53>, <53>, <53>, <53>,
                <53>, <53>, <53>, <53>,
                <53>, <53>, <53>, <53>,
                <53>, <53>, <53>, <53>;
        status = "okay";
};

&i2c0 {
        status = "okay";
};

&i2c1 {
        status = "okay";
        #address-cells = <1>;
        #size-cells = <0>;

        eeprom: eeprom@50 {
                compatible = "microchip,24aa025", "atmel,24c02";
        //compatible = "atmel,24c02";
                reg = <0x50>;
                #address-cells = <1>;
                #size-cells = <1>;
                eth0_addr: eth-mac-addr@FA {
                        reg = <0xFA 0x06>;
                };
        };
};


&mac0 {
        status = "okay";
        phy-mode = "sgmii";
        nvmem-cells = <&eth0_addr>;
        nvmem-cell-names = "mac-address";

        phy-handle = <&phy0>;
        phy0: ethernet-phy@1 {
                device-type = "ethernet-phy";
                reg = <1>;
                reset-names = "ETH_RST";
                reset-gpios = <&gpio1 16 GPIO_ACTIVE_LOW>;
        };
};

&mbox {
        status = "okay";
};

&mmc {
        status = "okay";
        bus-width = <4>;
        disable-wp;
        cap-sd-highspeed;
        cap-mmc-highspeed;
        // mmc-ddr-1_8v;
```

```
        // mmc-hs200-1_8v;
        sd-uhs-sdr12;
        sd-uhs-sdr25;
        sd-uhs-sdr50;
        sd-uhs-sdr104;
};


&mmuart1 {
        status = "okay";
};

&mmuart2 {
        status = "okay";
};

&mmuart3 {
        status = "okay";
};

&mmuart4 {
        status = "okay";
};


&qspi {
        status = "okay";
        num-cs = <1>;
};

&refclk {
        clock-frequency = <125000000>;
};


&spi0 {
        status = "okay";
};


&usb {
        status = "okay";
        dr_mode = "otg";
        // dr_mode = "host";
        phys = <&usb_phy>;
};

&syscontroller {
    status = "okay";
};
```

Kernel

File location: *<trenz BSP folder>/recipes-kernel/linux/*

Changes:

- CONFIG_CMDLINE_BOOL=y
- CONFIG_CMDLINE="earlycon=sbi root=/dev/mmcblk0p3 rootwait uio_pdrv_genirq.of_id=generic-uio"
- CONFIG_EEPROM_AT24=y
- CONFIG_NVMEM=y
- CONFIG_NVMEM_SYS=y
- CONFIG_REGMAP_I2C=y
- CONFIG_MARVELL_PHY=y
- CONFIG_LEDS_GPIO=y
- CONFIG_LEDS_CLASS=y
- CONFIG_NEW_LEDS=y
- CONFIG_GPIOLIB=y
- CONFIG_USB_MUSB_HOST=y
- CONFIG_USB_MUSB_DUAL_ROLE=y
- CONFIG_MTD_SPI_NOR_USE_4K_SECTORS=n
- CONFIG_MTD_UBI=y
- CONFIG_MTD_CMDLINE_PARTS=y
- CONFIG_UBIFS_FS=y
- CONFIG_MTD_SPI_NOR=y
- CONFIG_OF_OVERLAY=y
- CONFIG_OF_CONFIGFS=y
- CONFIG_MFD_SENSEHAT_CORE=m
- CONFIG_INPUT_JOYDEV=m
- CONFIG_INPUT_JOYSTICK=y
- CONFIG_JOYSTICK_SENSEHAT=m
- CONFIG_AUXDISPLAY=y
- CONFIG_SENSEHAT_DISPLAY=m
- CONFIG_HTS221=m
- CONFIG_IIO_ST_PRESS=m
- CONFIG_IIO_ST_LSM6DSX=m
- CONFIG_IIO_ST_MAGN_3AXIS=m
- #CONFIG_MUSB_PIO_ONLY is not set
- CONFIG_USB_INVENTRA_DMA=y

Images

Image recipe for minimal console image

File location: *<trenz BSP folder>/recipes-core/images/*

Image recipes:

- te-image-minimal.bb: create minimal linux image

Added packages/recipes:

- startup
- iputils-ping
- expect
- rsync
- rng-tools
- iperf3
- devmem2
- can-utils
- usbutils
- pciutils
- polarfire-soc-linux-examples
- dt-overlay-mchp
- libgpiod
- libgpiod-tools
- libgpiod-dev
- i2c-tools
- vim vim-vimrc
- net-tools
- htop
- iw
- python3

- python3-pip
- python3-flask
- python3-flask-dev
- python3-werkzeug
- libudev
- glib-2.0
- sqlite3
- dtc
- cmake
- tar
- wget
- zip
- mtd-utils
- mtd-utils-ubifs

Rootfs

Used filesystem: Root file system (RootFS)

Appx. A: Change History and Legal Notices

Document Change History

To get content of older revision got to "Change History" of this page and select older document revision number.

Date	Document Revision	Authors	Description
Error rendering macro 'page-info' Ambiguous method overloading for method jdk.proxy27.9.$Proxy	**Error rendering macro 'page-info'** Ambiguous method overloading for method jdk.proxy27.9.$Proxy	**Error rendering macro 'page-info'** Ambiguous method overloading for method jdk.proxy27.9.$Proxy	• Release for more variants • The design is matched to new carrier board TEB2000.

4022#ha sConten tLevelPe rmission . Cannot resolve which method to invoke for [null, class java. lang. String, class com. atlassian . confluen ce. pages. Page] due to overlapp ing prototyp es between : [interfac e com. atlassian . confluen ce.user. Conflue nceUser

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2023-11-13	v.57	Mohsen Chamanbaz	• Clock frequency of LPDDR4 reduced to 500MHz. • USB and ethernet phys will be reset while booting.
2023-09-08	v.56	Mohsen Chamanbaz	• Update download path

2023-09-07	v.54	Mohsen Chamanbaz	• Initial release v2023.1
--	all	**Error rendering macro 'page-info'** Ambiguous method overloading for method jdk.proxy279.$Proxy4022#hasContentLevelPermission. Cannot resolve which method to invoke for [null, class java.lang.String, class com.atlassian	--

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Document change history

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To confront directly with the responsibility toward the environment, the global community and eventually also oneself. Such a resolution should be integral part not only of everybody's life. Also enterprises shall be conscious of their social responsibility and contribute to the preservation of our common living space. That is why Trenz Electronic invests in the protection of our Environment.

REACH, RoHS and WEEE

REACH

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Trenz Electronic GmbH herewith declares that all its products are developed, manufactured and distributed RoHS compliant.

WEEE

Information for users within the European Union in accordance with Directive 2002/96/EC of the European Parliament and of the Council of 27 January 2003 on waste electrical and electronic equipment (WEEE).

Users of electrical and electronic equipment in private households are required not to dispose of waste electrical and electronic equipment as unsorted municipal waste and to collect such waste electrical and electronic equipment separately. By the 13 August 2005, Member States shall have ensured that systems are set up allowing final holders and distributors to return waste electrical and electronic equipment at least free of charge. Member States shall ensure the availability and accessibility of the necessary collection facilities. Separate collection is the precondition to ensure specific treatment and recycling of waste electrical and electronic equipment and is necessary to achieve the chosen level of protection of human health and the environment in the European Union. Consumers have to actively contribute to the success of such collection and the return of waste electrical and electronic equipment. Presence of hazardous substances in electrical and electronic equipment results in potential effects on the environment and human health. The symbol consisting of the crossed-out wheeled bin indicates separate collection for waste electrical and electronic equipment.

Trenz Electronic is registered under WEEE-Reg.-Nr. DE97922676.

Error rendering macro 'page-info'

Ambiguous method overloading for method jdk.proxy279.$Proxy4022#hasContentLevelPermission. Cannot resolve which method to invoke for [null, class java.lang.String, class com.atlassian.confluence.pages.Page] due

to overlapping prototypes between: [interface com.atlassian.confluence.user.
ConfluenceUser, class java.lang.String, class com.atlassian.confluence.core.
ContentEntityObject] [interface com.atlassian.user.User, class java.lang.String, class
com.atlassian.confluence.core.ContentEntityObject]