

TE0713 Test Board

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MicroBlaze Design With Linux example.

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Refer to <http://trac.terasic.com.tw/cgi-bin/viewsvn.cgi?root=1&path=/trac/wiki/TE0713-Test-Board-Release-Notes-for-the-current-version> online version of this manual and other available documentation.

- 1.4 Requirements

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For directly getting started with the prebuilt files jump to the section [Launch](#).

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Key Features

- Vitis/Vivado 2021.2
- Design Flow
- Petalinux
- Launch
- MIG
- FLASH

- 3.1 Programming

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Revision History

| Date | Project Built | Authors | Description |
|------------|---|----------------------|---|
| 2022-02-16 | TE0713-test_board_noprebui lt-vivado_2021.2- build_11_20220216 083114.zip TE0713-test_board- vivado_2021.2- build_11_20220216 083114.zip | Waldemar Hanemann | <ul style="list-style-type: none">• new spi bootloader by Henrik Brix Andersen• adjusted offsets |
| 2021-08-05 | TE0713- test_board_noprebui lt-vivado_2021.2- build_6_202201051 12236.zip TE0713-test_board- vivado_2021.2- build_6_202201051 12236.zip | Waldemar Hanemann | <ul style="list-style-type: none">• 2021.2 update• added distroboot |
| 2021-12-08 | TE0713- test_board_noprebui lt-vivado_2020.2- build_9_202112100 90602.zip TE0713-test_board- vivado_2020.2- build_9_202112100 90545.zip | Waldemar Hanemann | <ul style="list-style-type: none">• 2020.2 update• template style |
| 2020-07-09 | TE0713- test_board_noprebui lt-vivado_2019.2- build_13_20200709 071700.zip TE0713-test_board- vivado_2019.2- build_13_20200709 071613.zip | John Hartfiel | <ul style="list-style-type: none">• initial release |

Design Revision History

Release Notes and Know Issues

| Issues | Description | Workaround | To be fixed version |
|----------------------------------|-------------|---|--|
| petalinux-build failed on 2020.2 | --- | activate "Networking support" in petalinux-config -c u-boot | <ul style="list-style-type: none">implemented in vivado 2020.2 |

Known Issues

Requirements

Software

| Software | Version | Note |
|-----------|---------|--|
| Vitis | 2021.2 | needed, Vivado is included into Vitis installation |
| PetaLinux | 2021.2 | needed |

Software

Hardware

Basic description of TE Board Part Files is available on [TE Board Part Files](#).

Complete List is available on <design name>/board_files/*_board_files.csv

Design supports following modules:

| Module Model | Board Part Short Name | PCB Revision Support | DDR | QSPI Flash | EMMC | Others | Notes |
|-------------------|-----------------------|----------------------|-----|------------|------|--------|-------|
| TE0713-02-100-2c* | 100_2c | REV02 REV01 | 1GB | 32MB | NA | NA | NA |
| TE0713-02-200-2c | 200_2c | REV02 REV01 | 1GB | 32MB | NA | NA | NA |

*used as reference

Hardware Modules

Design supports following carriers:

| Carrier Model | Notes |
|---------------|-------|
| TE0701 | |
| TE0703* | |
| TE0705 | |
| TE0706 | |
| TEBA0841 | |

*used as reference

Hardware Carrier

Additional HW Requirements:

| Additional Hardware | Notes |
|-------------------------|--|
| USB Cable for JTAG/UART | Check Carrier Board and Programmer for correct typ |
| XMOD Programmer | Carrier Board dependent, only if carrier has no own FTDI |

Additional Hardware

Content

For general structure and of the reference design, see [Project Delivery - AMD devices](#)

Design Sources

| Type | Location | Notes |
|-----------|--|---|
| Vivado | <project folder>/block_design <project folder>/constraints <project folder>/ip_lib | Vivado Project will be generated by TE Scripts |
| Vitis | <project folder>/sw_lib | Additional Software Template for Vitis and apps_list.csv with settings automatically for Vitis app generation |
| PetaLinux | <project folder>/os/petalinux | PetaLinux template with current configuration |

Design sources

Additional Sources

| Type | Location | Notes |
|------|----------|-------|
| -- | -- | -- |

Additional design sources

Prebuilt

| File | File-Extension | Description |
|------------------|----------------|--|
| BIT-File | *.bit | FPGA (PL Part) Configuration File |
| Boot Source | *.scr | Distro Boot file |
| DebugProbes-File | *.ltx | Definition File for Vivado/Vivado Labtools Debugging Interface |
| Diverse Reports | --- | Report files in different formats |

| | | |
|---------------------------------------|--------|--|
| Hardware-Platform-Specification-Files | *.xsa | Exported Vivado Hardware Specification for Vitis and PetaLinux |
| LabTools Project-File | *.lpr | Vivado Labtools Project File |
| MCS-File | *.mcs | Flash Configuration File with Boot-Image (MicroBlaze or FPGA part only) |
| MMI-File | *.mmi | File with BRAM-Location to generate MCS or BIT-File with *.elf content (MicroBlaze only) |
| OS-Image | *.ub | Image with Linux Kernel (On Petalinux optional with Devicetree and RAM-Disk) |
| Software-Application-File | *.elf | Software Application for Zynq or MicroBlaze Processor Systems |
| SREC-File | *.srec | Converted Software Application for MicroBlaze Processor Systems |

Prebuilt files (only on ZIP with prebuilt content)

Download

Reference Design is only usable with the specified Vivado/Vitis/PetaLinux version. Do never use different Versions of Xilinx Software for the same Project.

Reference Design is available on:

- [TE0713 "Test Board" Reference Design](#)

Design Flow



Reference Design is available with and without prebuilt files. It's recommended to use TE prebuilt files for first launch.

Trenz Electronic provides a tcl based built environment based on Xilinx Design Flow.

See also:

- [AMD Development Tools#XilinxSoftware-BasicUserGuides](#)
- [Vivado Projects - TE Reference Design](#)
- [Project Delivery](#)

The Trenz Electronic FPGA Reference Designs are TCL-script based project. Command files for execution will be generated with "_create_win_setup.cmd" on Windows OS and "_create_linux_setup.sh" on Linux OS.

TE Scripts are only needed to generate the vivado project, all other additional steps are optional and can also executed by Xilinx Vivado/Vitis GUI. For current script limitations on Win and Linux OS see: [Project Delivery Currently limitations of functionality](#)



Caution! Win OS has a 260 character limit for path lengths which can affect the Vivado tools. To avoid this issue, use Virtual Drive or the shortest possible names and directory locations for the reference design (for example "x:\<project folder>")

1. Run `_create_win_setup.cmd/_create_linux_setup.sh` and follow instructions on shell:

```
_create_win_setup.cmd/_create_linux_setup.sh

-----Set design paths-----
-- Run Design with: _create_win_setup
-- Use Design Path: <absolute project path>
-----

-----TE Reference
Design-----
-----

-- (0) Module selection guide, project creation...prebuilt export...
-- (1) Create minimum setup of CMD-Files and exit Batch
-- (2) Create maximum setup of CMD-Files and exit Batch
-- (3) (internal only) Dev
-- (4) (internal only) Prod
-- (c) Go to CMD-File Generation (Manual setup)
-- (d) Go to Documentation (Web Documentation)
-- (g) Install Board Files from Xilinx Board Store (beta)
-- (a) Start design with unsupported Vivado Version (beta)
-- (x) Exit Batch (nothing is done!)
----
Select (ex.: '0' for module selection guide):
```

2. Press 0 and enter to start "Module Selection Guide"
3. (optional Win OS) Generate Virtual Drive or use short directory for the reference design (for example `x:\<design name>`)
4. Create project and follow instructions of the product selection guide, settings file will be configured automatically during this process.
 - optional for manual changes: Select correct device and Xilinx install path on "design_basic_settings.cmd" and create Vivado project with "vivado_create_project_gui mode.cmd"



Note: Select correct one, see also [Vivado Board Part Flow](#)

5. Create hardware description file (.xsa file) for PetaLinux project and export to prebuilt folder

run on Vivado TCL (Script generates design and export files into "<project folder>\prebuilt\hardware\<short name>")

```
TE::hw_build_design -export_prebuilt
```



Using Vivado GUI is the same, except file export to prebuilt folder.

6. Create and configure your PetaLinux project with exported .xsa-file, see [PetaLinux KICKstart](#)
 - use TE Template from "`<project folder>\os\petalinux`"
 - use exported .xsa file from "`<project folder>\prebuilt\hardware\<short name>`". **Note:** HW Export from Vivado GUI creates another path as default workspace.
 - The build images are located in the "`<plnx-proj-root>\images\linux`" directory
7. Configure the **boot.scr** file as needed, see [Distro Boot with Boot.scr](#)
8. Add Linux files (uboot.elf, image.ub, boot.scr) to prebuilt folder



- copy **u-boot.elf**, **image.ub** and **boot.scr** from "<plnx-proj-root>/images/linux" to prebuilt folder "<project folder>\prebuilt\os\petalinux\<ddr size>" or "<project folder>\prebuilt\os\petalinux\<short name>"

9. Generate Programming Files with Vitis

run on Vivado TCL (Script generates applications and bootable files, which are defined in "test_board\sw_lib\apps_list.csv")

```
TE::sw_run_vitis -all
TE::sw_run_vitis (optional: Start Vitis from Vivado GUI or start
with TE Scripts on Vivado TCL)
```



TCL scripts generate also platform project, this must be done manually in case GUI is used. See [Vitis](#)

10. (Optional) BlockRam Firmware Update

- a. Copy "<project folder>\prebuilt\software\<short name>\spi_bootloader.elf" into "<project folder>\firmware\microblaze_0\"
- b. Regenerate Vivado Project or Update Bitfile only with new "spi_bootloader.elf"

```
TE::hw_build_design -export_prebuilt
TE::sw_run_vitis -all
```

Launch

Programming



Check Module and Carrier TRMs for proper HW configuration before you try any design.

Reference Design is also available with prebuilt files. It's recommended to use TE prebuilt files for first launch.

Xilinx documentation for programming and debugging: [Vivado/Vitis/SDSoC-Xilinx Software Programming and Debugging](#)

Get prebuilt boot binaries

1. Run `_create_win_setup.cmd/_create_linux_setup.sh` and follow instructions on shell
2. Press 0 and enter to start "Module Selection Guide"
 - a. Select assembly version
 - b. Validate selection
 - c. Select Create and open delivery binary folder



Note: Folder "<project folder>_binaries_<Article Name>" with subfolder "boot_<app name>" for different applications will be generated

QSPI-Boot mode

Option for **u-boot.mcs** on QSPI Flash.
(u-boot.mcs contains all files necessary to boot up linux)

1. Connect the USB cable(**JTAG**) and **power supply** on carrier with module
2. Open Vivado Project with "vivado_open_existing_project_gui mode.cmd" or if not created, create with "vivado_create_project_gui mode.cmd".
Enter the following TCL-Command into the TCL-Console inside Vivado to program the QSPI Flash.

run on Vivado TCL (Script programs u-boot.mcs on QSPI flash)

```
TE::pr_program_flash -swapp u-boot
```

SD-Boot mode

Not used on this Example.

JTAG

Not used on this Example.

Usage

1. Prepare HW like described on section [Programming](#)
2. Connect UART USB (most cases same as JTAG)
3. Select QSPI as Boot Mode



Note: See TRM of the Carrier, which is used.

4. Power On PCB and push the reset button if present on carrier.
 1. FPGA Loads Bitfile from Flash,
 2. SPI Bootloader from Bitfile Firmware loads U-Boot into DDR,
 3. U-boot loads Linux from QSPI Flash into DDR

```
SPI ELF Bootloader
Copying ELF image from SPI flash @ 0x005e0000 to RAM
.....
Transferring execution to program @ 0x80100000


U-Boot 2021.01 (Oct 12 2021 - 09:28:42 +0000)

Model: Xilinx MicroBlaze
DRAM: 512 MiB
WDT: Not found!
In: serial
Out: serial
Err: serial
Model: Xilinx MicroBlaze
```

Boot process takes a while, please wait...


Linux

1. Open Serial Console (e.g. PuTTY)
 - Speed: 9600
 - select COM Port

 Win OS, see device manager, Linux OS see dmesg |grep tty (UART is *USB1)

2. Linux Console:

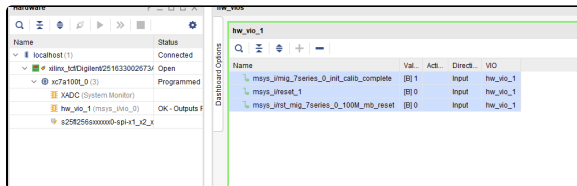
```
petalinux login: root
Password: root
```

 Note: Wait until Linux boot finished

Vivado HW Manager

Open Vivado HW-Manager and add VIO signal to dashboard (*.ltx located on prebuilt folder)

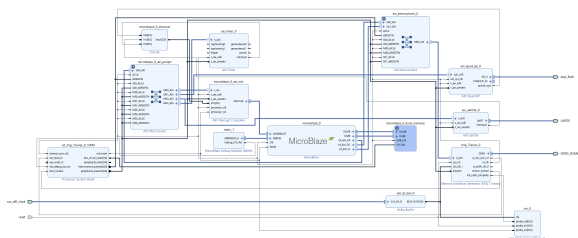
- Monitoring:
 - MIG Calibration Done
 - Main Reset
 - MicroBlaze Reset



Vivado Hardware-Manager

System Design - Vivado

Block Design



Block Design

Constraints

Basic module constraints

`_i_bitgen_common.xdc`

```
set_property BITSTREAM.GENERAL.COMPRESS TRUE [current_design]
set_property BITSTREAM.CONFIG.CONFIGRATE 66 [current_design]
set_property CONFIG_VOLTAGE 3.3 [current_design]
set_property CFGBVS VCCO [current_design]
set_property CONFIG_MODE SPIx4 [current_design]
set_property BITSTREAM.CONFIG.SPI_32BIT_ADDR YES [current_design]
set_property BITSTREAM.CONFIG.SPI_BUSWIDTH 4 [current_design]
set_property BITSTREAM.CONFIG.M1PIN PULLNONE [current_design]
set_property BITSTREAM.CONFIG.M2PIN PULLNONE [current_design]
set_property BITSTREAM.CONFIG.M0PIN PULLNONE [current_design]

set_property BITSTREAM.CONFIG.USR_ACCESS TIMESTAMP [current_design]
```

Design specific constraints

`_i_bitgen.xdc`

```
set_property BITSTREAM.CONFIG.UNUSEDPIN PULLDOWN [current_design]
#
#
#
```

Software Design - Vitis

For Vitis project creation, follow instructions from:

[Vitis](#)

Application

Template location: `./sw_lib/sw_apps/`

spi_bootloader

TE modified SPI Bootloader from [Henrik Brix Andersen](#).

Bootloader to load app or second bootloader from flash into DDR.

Here it loads the u-boot.elf from QSPI-Flash to RAM. Hence u-boot.srec becomes redundant.

Descriptions:

- Modified Files: `bootloader.c`

- Changes:
 - Change the SPI defines in the header
 - Add some reiteration in the frist spi read call

hello_te0713

Hello TE0713 is a Xilinx Hello World example as endless loop instead of one console output.

u-boot

U-Boot.elf is generated with PetaLinux. Vitis is used to generate the file u-boot.srec(obsolete). Vivado is used to generate the file *.mcs

Software Design - PetaLinux

For PetaLinux installation and project creation, follow instructions from:

- [PetaLinux KICKstart](#)

Config

Start with **petalinux-config** or **petalinux-config --get-hw-description**

(Tipp: Search for Settings with shortcut "Shift"+"/")

Changes:

- SUBSYSTEM_FLASH_AXI_QUAD_SPI_0_BANKLESS_PART0_SIZE = **0x5E0000** (fpga)
- SUBSYSTEM_FLASH_AXI_QUAD_SPI_0_BANKLESS_PART1_SIZE = **0x400000** (boot)
- SUBSYSTEM_FLASH_AXI_QUAD_SPI_0_BANKLESS_PART2_SIZE = **0x20000** (bootenv)
- SUBSYSTEM_FLASH_AXI_QUAD_SPI_0_BANKLESS_PART3_SIZE = **0xA00000** (kernel)
 - (with this kernel flash address is 0xA00000 (fpga+boot+bootenv) and Kernel size 0xA00000)

U-Boot

Start with **petalinux-config -c u-boot**

Changes: (e.g. activate CONFIG via petalinux GUI like [*] Environment is not stored)

- CONFIG_ENV_IS_NOWHERE=y
- # CONFIG_ENV_IS_IN_SPI_FLASH is not set

Content of **platform-top.h** located in <plnx-proj-root>/project-spec/meta-user/recipes-bsp/u-boot/files:

```
#include <configs/microblaze-generic.h>
#include <configs/platform-auto.h>

#define CONFIG_SYS_BOOTM_LEN 0xF000000
```

Device Tree

Content of **system-user.dtsi** located in <petalinux project directory>/project-spec/meta-user/recipes-bsp/device-tree/file:

```
/include/ "system-conf.dtsi"
/ {
};
```

Kernel

Start with **petalinux-config -c kernel**

Changes:

- No changes.

Rootfs

Start with **petalinux-config -c rootfs**

Changes:

- # CONFIG_dropbear is not set
- # CONFIG_dropbear-dev is not set
- # CONFIG_dropbear-dbg is not set
- # CONFIG_package-group-core-ssh-dropbear is not set
- # CONFIG_packagegroup-core-ssh-dropbear-dev is not set
- # CONFIG_packagegroup-core-ssh-dropbear-dbg is not set
- # CONFIG_imagefeature-ssh-server-dropbear is not set

Applications

No additional application.

Additional Software

No additional software is needed.

Appx. A: Change History and Legal Notices

Document Change History

To get content of older revision got to "Change History" of this page and select older document revision number.

| Date | Document Revision | Authors | Description |
|------|-------------------|---------|-------------|
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| 2022-01-05 | v.5 | Waldemar Hanemann | <ul style="list-style-type: none"> • 2021.2 release • added distroboot |
| 2021-12-08 | v.3 | Waldemar Hanemann | <ul style="list-style-type: none"> • 2020.2 release • petalinux workarounds |
| 2020-07-09 | v.1 | John Hartfiel | <ul style="list-style-type: none"> • 2019.2 initial release |
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Document change history.

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REACH, RoHS and WEEE

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Users of electrical and electronic equipment in private households are required not to dispose of waste electrical and electronic equipment as unsorted municipal waste and to collect such waste electrical and electronic equipment separately. By the 13 August 2005, Member States shall have ensured that systems are set up allowing final holders and distributors to return waste electrical and electronic equipment at least free of charge. Member States shall ensure the availability and accessibility of the necessary collection facilities. Separate collection is the precondition to ensure specific treatment and recycling of waste electrical and electronic equipment and is necessary to achieve the chosen level of protection of human health and the environment in the European Union. Consumers have to actively contribute to the success of such collection and the return of waste electrical and electronic equipment. Presence of hazardous substances in electrical and electronic equipment results in potential effects on the environment and human health. The symbol consisting of the crossed-out wheeled bin indicates separate collection for waste electrical and electronic equipment.

Trenz Electronic is registered under WEEE-Reg.-Nr. DE97922676.

Error rendering macro 'page-info'

Ambiguous method overloading for method jdk.

proxy279.\$Proxy4022#hasContentLevelPermission. Cannot resolve which method to invoke for [null, class java.lang.String, class com.atlassian.confluence.pages.Page] due to overlapping prototypes between: [interface com.atlassian.confluence.user.ConfluenceUser, class java.lang.String, class com.atlassian.confluence.core.ContentEntityObject] [interface com.atlassian.user.User, class java.lang.String, class com.atlassian.confluence.core.ContentEntityObject]