

TE0710 Test Board

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Revision History

Date	5 Software Design - Vitis	Project Built	Authors	Description
2024-02-19	<ul style="list-style-type: none">5.1 Vivado Config5.2 U-Boot5.3 Busybox5.4 Device Tree5.5 Kernel5.6 Rootfs5.7 Applications<ul style="list-style-type: none">5.7.1 eeprom <ul style="list-style-type: none">6 Additional Software7 App. A: Change History and Legal Notices	TE0710-test_board_noprebuilt-vivado_2023.2-build_4_20240219100859.zip TE0710-test_board-vivado_2023.2-build_4_20240219100859.zip	Waldemar Hanemann	<ul style="list-style-type: none">2023.2 update
2022-02-16	<ul style="list-style-type: none">7.1 Document Change History7.2 Legal Notices7.3 Data Privacy7.4 Document Warranty7.5 Limitation of Liability7.6 Copyright Notice7.7 Technology Licenses7.8 Environmental Protection7.9 REACH, RoHS and WEEE	TE0710-test_board_noprebuilt-vivado_2021.2-build_11_20220216112910.zip TE0710-test_board-vivado_2021.2-build_11_20220216112910.zip	Waldemar Hanemann	<ul style="list-style-type: none">new spi bootloader by Henrik Brix Andersenadjusted offsets

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2022-02-04	2021.2	TE0710-test_board-vivado_2021.2-build_11_20220208153036.zip TE0710-test_board_noprebuilt-vivado_2021.2-build_11_20220208153036.zip	Waldemar Hanemann	<ul style="list-style-type: none"> • 2021.2 update • document style update • added boot script • added eeprom interface for MAC address read-out • added simple sd card interface • added 2nd Ethernet Interface
2020-04-21	2019.2	TE0710-test_board-vivado_2019.2-build_10_20200421063949.zip TE0710-test_board_noprebuilt-vivado_2019.2-build_10_20200421064005.zip	John Hartfiel	<ul style="list-style-type: none"> • 2019.2 update
2018-03-29	2017.4	te0710-test_board-vivado_2017.4-build_07_20180329130739.zip te0710-test_board_noprebuilt-vivado_2017.4-build_07_20180329130757.zip	John Hartfiel	<ul style="list-style-type: none"> • initial release

Design Revision History

Release Notes and Known Issues

Issues	Description	Workaround	To be fixed version
No known issues	---	---	---

Known Issues

Requirements

Software

Software	Version	Note
Vitis	2023.2	needed, Vivado is included into Vitis installation
PetaLinux	2023.2	needed

Software

Hardware

Basic description of TE Board Part Files is available on [TE Board Part Files](#).

Complete List is available on "<project folder>\board_files*_board_files.csv"

Design supports following modules:

Module Model	Board Part Short Name	PCB Revision Support	DDR	QSPI Flash	EMMC	Others	Notes
TE0710-02-35-2CF	35_2cf_512mb	REV02	512MB	32MB	NA	NA	NA
TE0710-02-35-2IF	35_2if_512mb	REV02	512MB	32MB	NA	NA	NA
TE0710-02-100-2CF	100_2cf_512mb	REV02	512MB	32MB	NA	NA	NA
TE0710-02-100-2IF	100_2if_512mb	REV02	512MB	32MB	NA	NA	NA
TE0710-02-72I21-A	100_2if_512mb	REV02	512MB	32MB	NA	NA	NA
TE0710-02-S001	100_2cf_512mb	REV02	512MB	32MB	NA	NA	no ETH-PHY
TE0710-02-42I21-A	35_2if_512mb	REV02	512MB	32MB	NA	NA	NA
TE0710-02-S003	35_2if_512mb	REV02	512MB	32MB	NA	NA	NA
TE0710-03-42C21-A	35_2cf_512mb	REV03	512MB	32MB	NA	NA	NA
TE0710-03-42I21-A	35_2if_512mb	REV03	512MB	32MB	NA	NA	NA
TE0710-03-72C21-A*	100_2cf_512mb	REV03	512MB	32MB	NA	NA	NA
TE0710-03-72I21-A	100_2if_512mb	REV03	512MB	32MB	NA	NA	NA

*used as reference

Hardware Modules

Design supports following carriers:

Carrier Model	Notes
TE0701	
TE0703*	used as reference carrier
TE0705	
TE0706	
TEBA0841	

*used as reference

Hardware Carrier

Additional HW Requirements:

Additional Hardware	Notes
---------------------	-------

USB Cable for JTAG/UART	Check Carrier Board and Programmer for correct type
XMOD Programmer	Carrier Board dependent, only if carrier has no own FTDI

* used as reference

Additional Hardware

Content

For general structure and usage of the reference design, see [Project Delivery - AMD devices](#)

Design Sources

Type	Location	Notes
Vivado	<project folder>\block_design <project folder>\constraints <project folder>\ip_lib <project folder>\board_files	Vivado Project will be generated by TE Scripts
Vitis	<project folder>\sw_lib	Additional Software Template for Vitis and apps_list.csv with settings automatically for Vitis app generation
PetaLinux	<project folder>\os\petalinux	PetaLinux template with current configuration

Design sources

Additional Sources

Type	Location	Notes

Additional design sources

Prebuilt

File	File-Extension	Description
BIT-File	*.bit	FPGA (PL Part) Configuration File
Boot Script-File	*.scr	Distro Boot Script file
DebugProbes-File	*.ltx	Definition File for Vivado/Vivado Labtools Debugging Interface
Diverse Reports	---	Report files in different formats
Hardware-Platform-Specification-Files	*.xsa	Exported Vivado Hardware Specification for Vitis and PetaLinux
LabTools Project-File	*.lpr	Vivado Labtools Project File

OS-Image	*.ub	Image with Linux Kernel (On Petalinux optional with Devicetree and RAM-Disk)
Software-Application-File	*.elf	Software Application for Zynq or MicroBlaze Processor Systems

Prebuilt files (only on ZIP with prebuilt content)

Download

Reference Design is only usable with the specified Vivado/Vitis/PetaLinux version. Do never use different Versions of AMD Software for the same Project.

Reference Design is available on:

- [TE0710 "Test Board" Reference Design](#)

Design Flow



Reference Design is available with and without prebuilt files. It's recommended to use TE prebuilt files for first launch.

Trenz Electronic provides a tcl based built environment based on AMD Design Flow.

See also:

- [Xilinx Development Tools#XilinxSoftware-BasicUserGuides](#)
- [Vivado Projects - TE Reference Design](#)
- [Project Delivery](#).

The Trenz Electronic FPGA Reference Designs are TCL-script based project. Command files for execution will be generated with "_create_win_setup.cmd" on Windows OS and "_create_linux_setup.sh" on Linux OS.

TE Scripts are only needed to generate the vivado project, all other additional steps are optional and can also executed by AMD Vivado/Vitis GUI. For currently Scripts limitations on Win and Linux OS see: [Project Delivery Currently limitations of functionality](#)



Caution! Win OS has a 260 character limit for path lengths which can affect the Vivado tools. To avoid this issue, use Virtual Drive or the shortest possible names and directory locations for the reference design (for example "x:\<project folder>")

1. Run _create_win_setup.cmd/_create_linux_setup.sh and follow instructions on shell:

`_create_win_setup.cmd/_create_linux_setup.sh`

```
-----Set design paths-----
-- Run Design with: _create_win_setup
-- Use Design Path: <absolute project path>
-----
-----TE Reference
Design-----
-----
-- (0) Module selection guide, project creation...prebuilt export...
-- (1) Create minimum setup of CMD-Files and exit Batch
-- (2) Create maximum setup of CMD-Files and exit Batch
-- (3) (internal only) Dev
-- (4) (internal only) Prod
-- (c) Go to CMD-File Generation (Manual setup)
-- (d) Go to Documentation (Web Documentation)
-- (g) Install Board Files from Xilinx Board Store (beta)
-- (a) Start design with unsupported Vivado Version (beta)
-- (x) Exit Batch (nothing is done!)
-----
Select (ex.: '0' for module selection guide):
```

2. Press 0 and enter to start "Module Selection Guide"
3. Create project and follow instructions of the product selection guide, settings file will be configured automatically during this process.
 - optional for manual changes: Select correct device and AMD install path on "design_basic_settings.cmd" and create Vivado project with "vivado_create_project_gui mode.cmd"



Note: Select correct one, see also [Vivado Board Part Flow](#)

4. Create hardware description file (.xsa file) for PetaLinux project and export to prebuilt folder

run on Vivado TCL (Script generates design and export files into "<project folder>\prebuilt\hardware\<short name>")

```
TE::hw_build_design -export_prebuilt
```



Using Vivado GUI is the same, except file export to prebuilt folder.

5. Create and configure your PetaLinux project with exported .xsa-file, see [PetaLinux KICKstart](#)
 - use TE Template from "<project folder>\os\petalinux"
 - use exported .xsa file from "<project folder>\prebuilt\hardware\<short name>". **Note:** HW Export from Vivado GUI creates another path as default workspace.
 - **Important Note:** Select correct Flash partition offset on petalinux-config: Subsystem Auto HW Settings Flash Settings, FPGA+Boot+bootenv=0xA00000 (increase automatically generate Boot partition), increase image size to A:, see [Config](#)
 - The build images are located in the "<plnx-proj-root>/images/linux" directory
6. Configure the **boot.scr** file as needed, see [Distro Boot with Boot.scr](#)
7. Copy PetaLinux build image files to prebuilt folder
 - copy **u-boot.elf** and **image.ub** from "<plnx-proj-root>/images/linux" to prebuilt folder



"<project folder>\prebuilt\os\petalinux\<ddr size>" or "<project folder>\prebuilt\os\petalinux\<short name>"

8. Generate Programming Files with Vitis

run on Vivado TCL (Script generates applications and bootable files, which are defined in "test_board\sw_lib\apps_list.csv")

```
TE::sw_run_vitis -all
TE::sw_run_vitis (optional; Start Vitis from Vivado GUI or start with TE Scripts on Vivado TCL)
```



TCL scripts generate also platform project, this must be done manually in case GUI is used. See [Vitis](#)

9. (Optional) BlockRam Firmware Update

- Copy "<project folder>\prebuilt\software\<short name>\spi_bootloader.elf" into "<project folder>\firmware\microblaze_0\"
- Regenerate Vivado Project or Update Bitfile only with "spi_bootloader.elf"

```
TE::hw_build_design -export_prebuilt
TE::sw_run_vitis -all
```

Launch

Programming



Check Module and Carrier TRMs for proper HW configuration before you try any design.

Reference Design is also available with prebuilt files. It's recommended to use TE prebuilt files for first launch.

AMD documentation for programming and debugging: [Vivado/Vitis/SDSoC-Xilinx Software Programming and Debugging](#)

Get prebuilt boot binaries

- Run `_create_win_setup.cmd/_create_linux_setup.sh` and follow instructions on shell
- Press 0 and enter to start "Module Selection Guide"
 - Select assembly version
 - Validate selection
 - Select create and open delivery binary folder



Note: Folder "<project folder>_binaries_<Article Name>" with subfolder "boot_<app name>" for different applications will be generated

QSPI-Boot mode

Option for **u-boot.mcs** on QSPI Flash.
(u-boot.mcs contains all files necessary to boot up linux)

1. Connect the **USB cable**(JTAG) and **power supply** on carrier with module
2. Open Vivado Project with "vivado_open_existing_project_gui mode.cmd" or if not created, create with "vivado_create_project_gui mode.cmd"

run on Vivado TCL (Script programs BOOT.bin on QSPI flash)

```
TE::pr_program_flash -swapp u-boot
```

3. Reboot (if not done automatically)

SD-Boot mode


Not used on this Example.


JTAG

Not used on this example.

Usage

1. Prepare HW like described on section [Programming](#)
2. Connect UART USB (most cases same as JTAG)
3. Select SD Card as Boot Mode (or QSPI - depending on step 1)

 Note: See TRM of the Carrier, which is used.

 Starting with Petalinux version 2020.1, the industry standard "Distro-Boot" boot flow for U-Boot was introduced, which significantly expands the possibilities of the boot process and has the primary goal of making booting much more standardised and predictable.
The boot options described above describe the common boot processes for this hardware; other boot options are possible.
For more information see [Distro Boot with Boot.scr](#)

4. Power On PCB
 1. FPGA Loads Bitfile from Flash,
 2. SPI Bootloader from Bitfile Firmware loads U-Boot into DDR (This takes a while)

```
SPI ELF Bootloader
Copying ELF image from SPI flash @ 0x005e0000 to RAM
.....
Transferring execution to program @ 0x80100000

U-Boot 2023.01 (Sep 21 2023 - 11:02:37 +0000)

Model: Xilinx MicroBlaze
```

3. U-boot loads Linux from QSPI Flash into DDR


Linux

1. Open Serial Console (e.g. putty)
 - Speed: 9600
 - select COM Port

 Win OS, see device manager, Linux OS see `dmesg |grep tty` (UART is *USB1)

2. Linux Console:

```
root@petalinux:
```

 **Note:** Wait until Linux boot finished, autologin is activated.

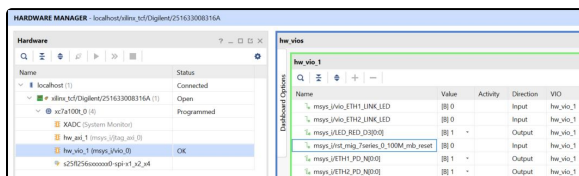
3. You can use Linux shell now.

udhcpc (ETH0 check)

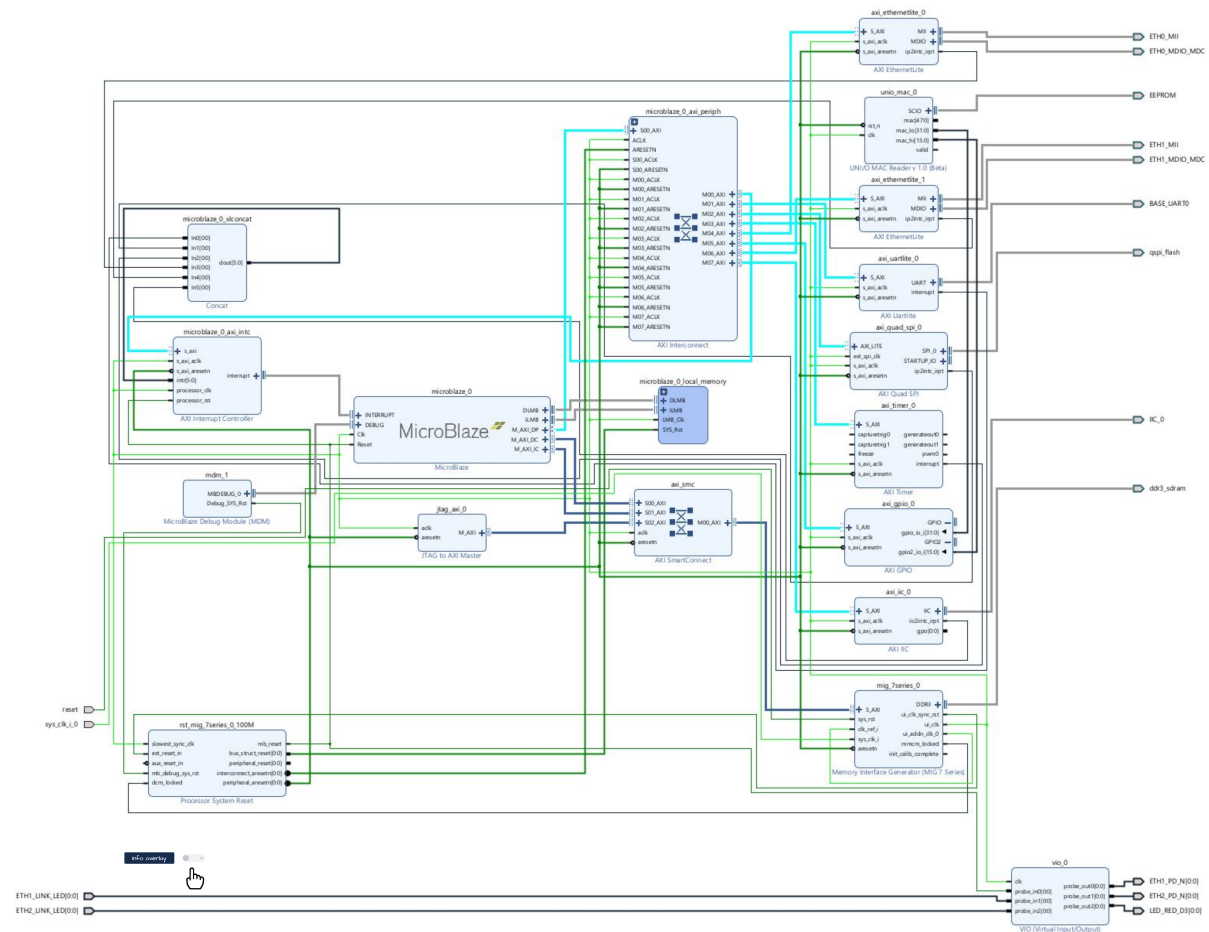
Vivado HW Manager

Open Vivado HW-Manager and add VIO signal to dashboard (*.ltx located on prebuilt folder)

- **Control:**
 - User LED Control
 - ETH Power Down
- **Monitoring:**
 - ETH Link Status
 - MicroBlaze Reset Status



Block Design



Block Design

Constraints

Basic module constraints

`_i_bitgen_common.xdc`

```
set_property BITSTREAM.GENERAL.COMPRESS TRUE [current_design]
set_property BITSTREAM.CONFIG.CONFIGRATE 66 [current_design]
set_property CONFIG_VOLTAGE 3.3 [current_design]
set_property CFGBVS VCCO [current_design]
set_property BITSTREAM.CONFIG.SPI_32BIT_ADDR YES [current_design]
set_property BITSTREAM.CONFIG.SPI_BUSWIDTH 4 [current_design]
set_property BITSTREAM.CONFIG.M1PIN PULLNONE [current_design]
set_property BITSTREAM.CONFIG.M2PIN PULLNONE [current_design]
set_property BITSTREAM.CONFIG.M0PIN PULLNONE [current_design]

set_property BITSTREAM.CONFIG.USR_ACCESS TIMESTAMP [current_design]
```

`_i_bitgen.xdc`

```
set_property BITSTREAM.CONFIG.UNUSEDPIN PULLDOWN [current_design]
```

Design specific constraints

`_i_io.xdc`

```
## set_property PACKAGE_PIN G3 [get_ports {LED_RED_XA_SC[0]}]
## set_property IOSTANDARD LVCMOS15 [get_ports {LED_RED_XA_SC[0]}]

set_property PACKAGE_PIN T10 [get_ports {ETH2_LINK_LED[0]}]
set_property IOSTANDARD LVCMOS33 [get_ports {ETH2_LINK_LED[0]}]
set_property PACKAGE_PIN V15 [get_ports {ETH1_LINK_LED[0]}]
set_property IOSTANDARD LVCMOS33 [get_ports {ETH1_LINK_LED[0]}]
set_property PACKAGE_PIN T18 [get_ports {ETH1_PD_N[0]}]
set_property PACKAGE_PIN D10 [get_ports {ETH2_PD_N[0]}]
set_property IOSTANDARD LVCMOS33 [get_ports {ETH2_PD_N[0]}]
set_property IOSTANDARD LVCMOS33 [get_ports {ETH1_PD_N[0]}]

set_property PACKAGE_PIN L15 [get_ports {LED_RED_D3[0]}]
set_property IOSTANDARD LVCMOS33 [get_ports {LED_RED_D3[0]}]

#EEPROM onewire (MAC ADDRESS)
set_property IOSTANDARD LVCMOS33 [get_ports EEPROM_tri_io]
set_property PACKAGE_PIN D9 [get_ports EEPROM_tri_io]

## IIC Interface
set_property PACKAGE_PIN G3 [get_ports IIC_0_sda_io]
set_property PACKAGE_PIN J5 [get_ports IIC_0_scl_io]
set_property IOSTANDARD LVCMOS15 [get_ports IIC_0_scl_io]
set_property IOSTANDARD LVCMOS15 [get_ports IIC_0_sda_io]
```

Software Design - Vitis

For Vitis project creation, follow instructions from:

[Vitis](#)

Application

Template location: "<project folder>\sw_lib\sw_apps\"

spi_bootloader

TE modified SPI Bootloader from [Henrik Brix Andersen](#).

Bootloader to load app or second bootloader from flash into DDR.

Here it loads the u-boot.elf from QSPI-Flash to RAM.

Descriptions:

- Modified Files: bootloader.c
- Changes:
 - Change the SPI defines in the header
 - Add some reiteration in the frist spi read call

hello_te0710

Hello TE0710 is a Hello World example as endless loop instead of one console output.

u-boot

U-Boot.elf is generated with PetaLinux. Vivado is used to generate *.mcs

Software Design - PetaLinux

For PetaLinux installation and project creation, follow instructions from:

- [PetaLinux KICKstart](#)

Config

Start with **petalinux-config** or **petalinux-config --get-hw-description**

Changes:

- SUBSYSTEM_FLASH_AXI_QUAD_SPI_0_BANKLESS_PART0_SIZE = **0x5E0000** (fpga)
- SUBSYSTEM_FLASH_AXI_QUAD_SPI_0_BANKLESS_PART1_SIZE = **0x400000** (boot)
- SUBSYSTEM_FLASH_AXI_QUAD_SPI_0_BANKLESS_PART2_SIZE = **0x200000** (bootenv)
- SUBSYSTEM_FLASH_AXI_QUAD_SPI_0_BANKLESS_PART3_SIZE = **0xD00000** (kernel)
 - (Set kernel flash Address to 0xA00000 (fpga+boot+bootenv) and Kernel size to 0xD00000)

U-Boot

Start with **petalinux-config -c u-boot**

Changes:

- CONFIG_ENV_IS_NOWHERE=y
- # CONFIG_ENV_IS_IN_SPI_FLASH is not set
- # CONFIG_PHY_ATHEROS is not set
- # CONFIG_PHY_BROADCOM is not set
- # CONFIG_PHY_DAVICOM is not set
- # CONFIG_PHY_LXT is not set
- # CONFIG_PHY_MICREL_KSZ90X1 is not set
- # CONFIG_PHY_MICREL is not set
- # CONFIG_PHY_NATSEMI is not set
- # CONFIG_PHY_REALTEK is not set
- CONFIG_RGMII=y

Busybox

Start with **petalinux-config -c busybox**

- Miscellaneous Utilities activate i2cget, i2cset, i2cdetect

Content of **platform-top.h** located in <plnx-proj-root>\project-spec\meta-user\recipes-bsp\u-boot\files:

```
#include <configs/microblaze-generic.h>
#include <configs/platform-auto.h>

#define CONFIG_SYS_BOOTM_LEN 0xF000000
```

Device Tree

Content of **system-user.dtsi** located in <petalinux project directory>\project-spec\meta-user\recipes-bsp\device-tree\files:

```

/include/ "system-conf.dtsi"
/ {
};

/* QSPI PHY */

&axi_quad_spi_0 {
    #address-cells = <1>;
    #size-cells = <0>;
    flash0: flash@0 {
        compatible = "jedec,spi-nor";
        spi-tx-bus-width=<1>;
        spi-rx-bus-width=<4>;
        reg = <0x0>;
        #address-cells = <1>;
        #size-cells = <1>;
        spi-max-frequency = <25000000>;
    };
};

/* ETH PHY */
&axi_ethernetlite_0 {
    phy-handle = <&phy0>;
    mdio {
        #address-cells = <1>;
        #size-cells = <0>;
        phy0: phy@0 {
            device_type = "ethernet-phy";
            reg = <1>;
        };
    };
};

/* ETH PHY 2nd */
&axi_ethernetlite_1 {

    phy-handle = <&phy1>;
    mdio {
        #address-cells = <1>;
        #size-cells = <0>;
        phy1: phy@1 {
            device_type = "ethernet-phy";
            reg = <1>;
        };
    };
};

/* i2c */
&axi_iic_0 {
    clock-frequency = <100000>;
    status = "okay";
};

```

Kernel

Start with **petalinux-config -c kernel**

Changes:

- No changes.

Rootfs

Start with **petalinux-config -c rootfs**

Changes:

- # CONFIG_dropbear is not set
- # CONFIG_dropbear-dev is not set
- # CONFIG_dropbear-dbg is not set
- # CONFIG_packagegroup-core-ssh-dropbear is not set
- # CONFIG_packagegroup-core-ssh-dropbear-dev is not set
- # CONFIG_packagegroup-core-ssh-dropbear-dbg is not set
- # CONFIG_imagefeature-ssh-server-dropbear is not set
- CONFIG_imagefeature-serial-autologin-root = y

Applications

See "<project folder>\os\petalinux\project-spec\meta-user\recipes-apps\"

eeeprom

eeeprom is a simple bash script implemented in petalinux as an application that executes on startup. It reads the unique 48-bit MAC from the onboard eeeprom and uses it to set the system MAC address.

Additional Software

No additional software is needed.

App. A: Change History and Legal Notices

Document Change History

To get content of older revision go to "Change History" of this page and select older document revision number.

Date	Document Revision	Authors	Description
			<ul style="list-style-type: none">• Release 2023.2

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2022-02-16	v.9	John Hartfiel	<ul style="list-style-type: none"> • bugfix documenten style
2022-02-16	v.8	Waldemar Hanemann	<ul style="list-style-type: none"> • new spi bootloader by Henrik Brix Andersen • adjusted offsets
2022-02-14	v.7	Waldemar Hanemann	<ul style="list-style-type: none"> • 2021.2 update • document style update • added boot script • added eeprom interface for MAC address read-out • added simple sd card interface • added 2nd Ethernet Interface
2020-04-21	v.5	John Hartfiel	<ul style="list-style-type: none"> • Release 2019.2 • Docu update
2019-03-29	v.4	John Hartfiel	<ul style="list-style-type: none"> • Release 2017.4
2019-03-29	v.1	<div> <div>Error rendering macro 'page-info'</div> <div>Ambiguous method</div> </div>	<ul style="list-style-type: none"> • Initial release

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Document change history.

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Data Privacy

Please also note our data protection declaration at <https://www.trenz-electronic.de/en/Data-protection-Privacy>

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Trenz Electronic is registered under WEEE-Reg.-Nr. DE97922676.

Error rendering macro 'page-info'

Ambiguous method overloading for method jdk.
proxy279.\$Proxy4022#hasContentLevelPermission. Cannot resolve which method to
invoke for [null, class java.lang.String, class com.atlassian.confluence.pages.Page] due
to overlapping prototypes between: [interface com.atlassian.confluence.user.
ConfluenceUser, class java.lang.String, class com.atlassian.confluence.core.
ContentEntityObject] [interface com.atlassian.user.User, class java.lang.String, class
com.atlassian.confluence.core.ContentEntityObject]