

TE0821 CR00200 Demo

Overview

Demonstration design for the CRUVI module board CR00200 in combination with the carrier board TEB0707-02 and the module board TE0821. The design implements a Linux example with web server application suitable for ZynqMP access via the Ethernet interface of the CRUVI module. The signals implemented in the VIO can be displayed and controlled by the Vivado HW Manager.

Wiki Resources page has links to the following issues

- 1.4 Requirements
 - 1.4.1 Software
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Key Features

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- Modified FSBL for SI5338 programming

Revision History

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Date	Project Built	Authors	Description
2022-12-06	TE0821-CR00200_demo-vivado_2021.2-build_20_20221206113615.zip	Manuela Strücker	<ul style="list-style-type: none"> • initial release

Design Revision History

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Release Notes and Know Issues

Issues	Description	Workaround	To be fixed version
Random MAC address	MAC address for eth is random and not used by the CRUVI EEPROM	update of CPLD firmware is necessary	-

Known Issues

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Requirements

Software

Software	Version	Note
Vitis	2021.2.1	needed Vivado is included into Vitis installation

PetaLinux	2021.2	needed
SI ClockBuilder Pro	---	optional

Software

Hardware

Design supports following modules:

Module Model	PCB Revision Support	Notes
CR00200-01*	REV01	NA

*used as reference

Hardware Modules

Design supports following carriers:

Carrier Model	Notes
TE0821-01-3BE21ML*	<ul style="list-style-type: none"> See TE0821 Test Board
TEB0707-02*	<ul style="list-style-type: none"> See TEB0707 TRM

*used as reference

Hardware Carrier

Additional HW Requirements:

Additional Hardware	Notes
USB Cable for JTAG/UART	Check Carrier Board and Programmer for correct type
XMOD Programmer	Carrier Board dependent, only if carrier has no own FTDI
Cooler	It's recommended to use cooler on ZynqMP device

*used as reference

Additional Hardware

Content

For general structure and of the reference design, see [Project Delivery - AMD devices](#)

Design Sources

Type	Location	Notes
------	----------	-------

Vivado	<project folder>\block_design <project folder>\constraints <project folder>\ip_lib <project folder>\board_files	Vivado Project will be generated by TE Scripts
Vitis	<project folder>\sw_lib	Additional Software Template for Vitis and apps_list.csv with settings automatically for Vitis app generation
PetaLinux	<project folder>\os\petalinux	PetaLinux template with current configuration

Design sources

Additional Sources

Type	Location	Notes
SI5338	<project folder>\misc\PLL\SI5338_B	SI5338 Project with current PLL Configuration
init.sh	<project folder>\misc\sd	Additional Initialization Script for Linux

Additional design sources

Prebuilt

File	File-Extension	Description
BIF-File	*.bif	File with description to generate Bin-File
BIN-File	*.bin	Flash Configuration File with Boot-Image (Zynq-FPGAs)
BIT-File	*.bit	FPGA (PL Part) Configuration File
Boot Script-File	*.scr	Distro Boot Script file
DebugProbes-File	*.ltx	Definition File for Vivado/Vivado Labtools Debugging Interface
Diverse Reports	---	Report files in different formats
Device Tree	*.dts	Device tree (2 possible, one for u-boot and one for linux)
Hardware-Platform-Description-File	*.xsa	Exported Vivado hardware description file for Vitis and PetaLinux
LabTools Project-File	*.lpr	Vivado Labtools Project File
OS-Image	*.ub	Image with Linux Kernel (On Petalinux optional with Devicetree and RAM-Disk)
Software-Application-File	*.elf	Software Application for Zynq or MicroBlaze Processor Systems

Prebuilt files (only on ZIP with prebuilt content)

Download

Reference Design is only usable with the specified Vivado/Vitis/PetaLinux version. Do never use different Versions of Xilinx Software for the same Project.

Reference Design is available on:

- [TE0821 "CR00200" Demonstration Design](#)

Design Flow



Reference Design is available with and without prebuilt files. It's recommended to use TE prebuilt files for first launch.

Trenz Electronic provides a tcl based built environment based on Xilinx Design Flow.

See also:

- [AMD Development Tools#XilinxSoftware-BasicUserGuides](#)
- [Vivado Projects - TE Reference Design](#)
- [Project Delivery](#).

The Trenz Electronic FPGA Reference Designs are TCL-script based project. Command files for execution will be generated with "_create_win_setup.cmd" on Windows OS and "_create_linux_setup.sh" on Linux OS.

TE Scripts are only needed to generate the vivado project, all other additional steps are optional and can also executed by Xilinx Vivado/Vitis GUI. For currently Scripts limitations on Win and Linux OS see: [Project Delivery Currently limitations of functionality](#)



Caution! Win OS has a 260 character limit for path lengths which can affect the Vivado tools. To avoid this issue, use Virtual Drive or the shortest possible names and directory locations for the reference design (for example "x:\<project folder>")

1. Run _create_win_setup.cmd/_create_linux_setup.sh and follow instructions on shell:

`_create_win_setup.cmd/_create_linux_setup.sh`

```
-----Set design paths-----
-- Run Design with: _create_win_setup
-- Use Design Path: <absolute project path>
-----
-----TE Reference Design-----
-----
-- (0) Module selection guide, project creation...prebuilt export...
-- (1) Create minimum setup of CMD-Files and exit Batch
-- (2) Create maximum setup of CMD-Files and exit Batch
-- (3) (internal only) Dev
-- (4) (internal only) Prod
-- (c) Go to CMD-File Generation (Manual setup)
-- (d) Go to Documentation (Web Documentation)
-- (g) Install Board Files from Xilinx Board Store (beta)
-- (a) Start design with unsupported Vivado Version (beta)
-- (x) Exit Batch (nothing is done!)
-----
Select (ex.: '0' for module selection guide):
```

2. Press 0 and enter to start "Module Selection Guide"
3. Create project and follow instructions of the product selection guide, settings file will be configured automatically during this process.
 - optional for manual changes: Select correct device and Xilinx install path on "design_basic_settings.cmd" and create Vivado project with "vivado_create_project_guiemode.cmd"

 Note: Select correct one, see also [Vivado Board Part Flow](#)

4. Create hardware description file (.xsa file) for PetaLinux project and export to prebuilt folder

run on Vivado TCL (Script generates design and export files into "<project folder>\prebuilt\hardware\<short name>")

```
TE::hw_build_design -export_prebuilt
```

 Using Vivado GUI is the same, except file export to prebuilt folder.

5. Create and configure your PetaLinux project with exported .xsa-file, see [PetaLinux KICKstart](#)
 - use TE Template from "<project folder>\os\petalinux"
 - use exported .xsa file from "<project folder>\prebuilt\hardware\<short name>". **Note:** HW Export from Vivado GUI creates another path as default workspace.
 - The build images are located in the "<plnx-proj-root>/images/linux" directory
6. Configure the **boot.scr** file as needed, see [Distro Boot with Boot.scr](#)
7. Copy PetaLinux build image files to prebuilt folder
 - copy **u-boot.elf**, **system.dtb**, **image.ub**, **bl31.elf** and **boot.scr** from "<plnx-proj-root>/images/linux" to prebuilt folder

 "<project folder>\prebuilt\os\petalinux\<ddr size>" or "<project folder>\prebuilt\os\petalinux\<short name>"

8. Generate Programming Files with Vitis

run on Vivado TCL (Script generates applications and bootable files, which are defined in "test_board\sw_lib\apps_list.csv")

```
TE::sw_run_vitis -all
TE::sw_run_vitis (optional; Start Vitis from Vivado GUI or start with TE
Scripts on Vivado TCL)
```

 TCL scripts generate also platform project, this must be done manually in case GUI is used. See [Vitis](#)

Launch

Programming



Check Module and Carrier TRMs for proper HW configuration before you try any design.

Reference Design is also available with prebuilt files. It's recommended to use TE prebuilt files for first launch.

Xilinx documentation for programming and debugging: [Vivado/Vitis/SDSoC-Xilinx Software Programming and Debugging](#)

Note: Depending on CPLD Firmware and Boot Mode settings, QSPI boot with Linux image on SD or complete SD Boot is possible.

Get prebuilt boot binaries

1. Run `_create_win_setup.cmd/_create_linux_setup.sh` and follow instructions on shell
2. Press 0 and enter to start "Module Selection Guide"
 - a. Select assembly version
 - b. Validate selection
 - c. Select Create and open delivery binary folder



Note: Folder "`<project folder>_binaries_<Article Name>`" with subfolder "`boot_<app name>`" for different applications will be generated

SD-Boot mode

1. Copy **image.ub**, **boot.src** and **Boot.bin** on SD
 - use files from "`<project folder>_binaries_<Article Name>\boot_linux`" from generated binary folder, see: [Get prebuilt boot binaries](#)
 - or use prebuilt file location, see "`<project folder>\prebuilt\file_location.txt`"
2. Set Boot Mode to SD-Boot.
 - Depends on Carrier, see carrier TRM.
3. Insert SD-Card in SD-Slot.

JTAG

Not used on this Example.

Usage

1. Prepare HW like described on section [Programming](#)
2. Connect UART USB (most cases same as JTAG)
3. Select SD Card or QSPI as Boot Mode (Depends on used programming variant)



Note: See TRM of the Carrier, which is used.



Starting with Petalinux version 2020.1, the industry standard "Distro-Boot" boot flow for U-Boot was introduced, which significantly expands the possibilities of the boot process and has the primary goal of making booting much more standardised and predictable. The boot options described above describe the common boot processes for this hardware; other boot options are possible. For more information see [Distro Boot with Boot.scr](#)

4. Power On PCB

1. ZynqMP Boot ROM loads PMU Firmware and FSBL from SD/QSPI Flash into OCM
2. FSBL init PS, programs PL using the bitstream and loads U-boot from SD into DDR,
3. U-boot loads Linux (**image.ub**) from SD/QSPI/... into DDR

Linux

1. Open Serial Console (e.g. putty)
 - a. Speed: 115200
 - b. Select COM Port

 Win OS, see device manager, Linux OS see dmesg |grep tty (UART is *USB1)

2. Linux Console:

```
# password default disabled with 2021.2 petalinux release
petalinux login: root
Password: root
```

 Note: Wait until Linux boot finished

3. You can use Linux shell now.

```
Ethernet
    ifconfig                               (display all active interface details)
```

4. Option Features

- Webservice to get access to Zynq
 - insert IP on web browser to start web interface
- init.sh scripts
 - add init.sh script on SD, content will be load automatically on startup (template included in "<project folder>\misc\SD")

Vivado HW Manager

Open Vivado HW-Manager and add VIO signal to dashboard (*.ltx located on prebuilt folder)

Monitoring:

- SI5338_CLKx Counter:
 - Set radix from VIO signals to unsigned integer.
 - Note: Frequency Counter is inaccurate and displayed unit is Hz for CLK signals
- SI5338 CLK0 is configured to 200MHz by default and SI5338 CLK3 is configured to 125MHz by default.
- CR00200_Phy_CLK125 measured CRUVI Phy CLK125 clock signal with 125MHz
- GMII_to_RGMII output signals
 - link status
 - clock speed
 - duplex_status
 - speed_mode

- CR00200_Phy Interrupt Signal

Control:

- LED over X0/X1 , see [TE0821 CPLD#LED](#)

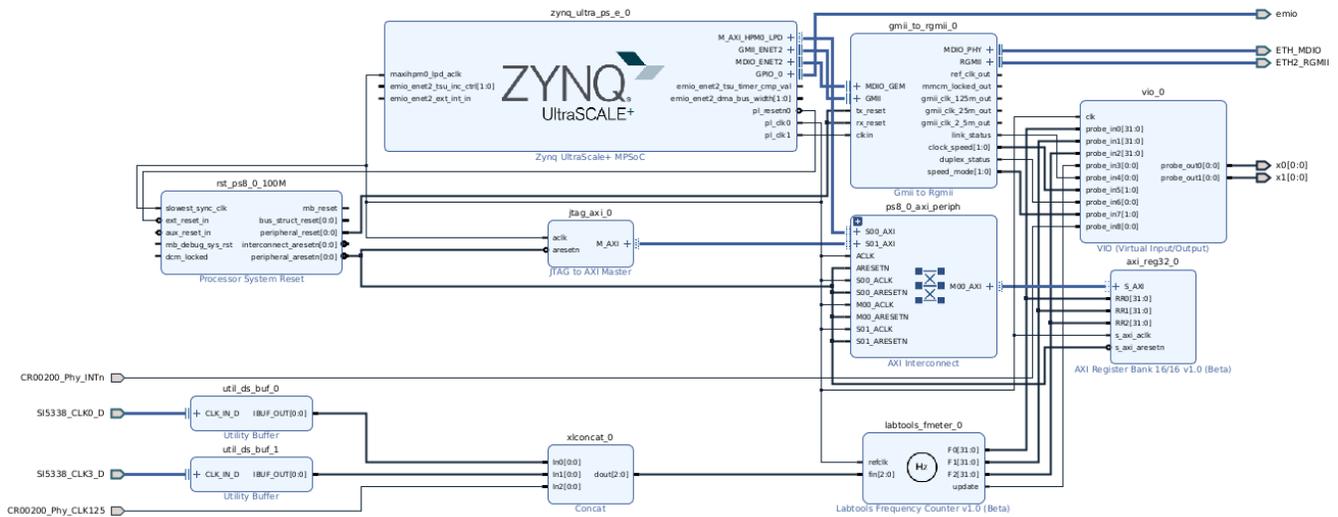
The screenshot shows the Vivado Hardware Manager interface. On the left is a project tree with components like 'xczu3_0', 'SysMon', 'hw_axi_1', 'hw_vio_1', and 'arm_dap_1'. The main area displays a table of signals with their current values and activity. A context menu is open over the 'Radix' property of the selected signal, showing options: Binary, Octal, Hex, **Unsigned Decimal** (selected), and Signed Decimal.

Name	Value	Activity	Direction	VIO
zsys_ifm_SI5338_CLK0_D[31:0]	[U] 200000152		Input	bus_vio_1
zsys_iflabtools_fmeter_0_F1[31:0]	[U] 125000095			
zsys_iflabtools_fmeter_0_F2[31:0]	[U] 124999902			
zsys_iflabtools_fmeter_0_update	[B] 0			
zsys_ifgmii_to_rgmii_0_link_status	[B] 1			
zsys_ifgmii_to_rgmii_0_clock_speed[1:0]	[B] 10			
zsys_ifgmii_to_rgmii_0_duplex_status	[B] 1			
zsys_ifgmii_to_rgmii_0_speed_mode[1:0]	[B] 10			
zsys_ifCR00200_Phy_INTn_1	[B] 0			
zsys_ix0[0:0]	[B] 0			
zsys_ix1[0:0]	[B] 1			

Vivado Hardware Manager

System Design - Vivado

Block Design



Block Design

PS Interfaces

Activated interfaces:

Type	Note
DDR	
QSPI	MIO
SD0	MIO
SD1	MIO
I2C0	MIO
UART0	MIO
GPIO	EMIO (1)
GPIO0	MIO
SWDT0..1	
TTC0..3	
GEM2	EMIO
USB0	MIO, USB2 only

PS Interfaces

Constrains

Basic module constrains

`_i_bitgen_common.xdc`

```
set_property BITSTREAM.GENERAL.COMPRESS TRUE [current_design]
set_property BITSTREAM.CONFIG.UNUSEDPIN PULLNONE [current_design]
```

Design specific constrain

`_i_io.xdc`

```
#SI5338
set_property PACKAGE_PIN E5 [get_ports {SI5338_CLK0_D_clk_p[0]}]
set_property IOSTANDARD LVDS [get_ports {SI5338_CLK0_D_clk_p[0]}]
set_property PACKAGE_PIN C3 [get_ports {SI5338_CLK3_D_clk_p[0]}]
set_property IOSTANDARD LVDS [get_ports {SI5338_CLK3_D_clk_p[0]}]
```

```
#CPLD
set_property PACKAGE_PIN B1 [get_ports {x0[0]}]
set_property IOSTANDARD LVCMOS18 [get_ports {x0[0]}]
set_property PACKAGE_PIN C1 [get_ports {x1[0]}]
set_property IOSTANDARD LVCMOS18 [get_ports {x1[0]}]
```

```
#Ethernet
```

```

#IO Placement
set_property PACKAGE_PIN R7 [get_ports {emio_tri_io[0]}]
set_property IOSTANDARD LVCMOS18 [get_ports {emio_tri_io[0]}]

set_property PACKAGE_PIN T7 [get_ports {CR00200_Phy_INTn}]
set_property IOSTANDARD LVCMOS18 [get_ports {CR00200_Phy_INTn}]

set_property PACKAGE_PIN L3 [get_ports {CR00200_Phy_CLK125}]
set_property IOSTANDARD LVCMOS18 [get_ports {CR00200_Phy_CLK125}]

#CR00200 --> TEB0707 J11 --> TE0821
set_property PACKAGE_PIN N9 [get_ports {ETH2_RGMII_txc}]
set_property PACKAGE_PIN N8 [get_ports {ETH2_RGMII_tx_ctl}]
set_property PACKAGE_PIN M8 [get_ports {ETH2_RGMII_td[0]}]
set_property PACKAGE_PIN L8 [get_ports {ETH2_RGMII_td[1]}]
set_property PACKAGE_PIN K7 [get_ports {ETH2_RGMII_td[2]}]
set_property PACKAGE_PIN K8 [get_ports {ETH2_RGMII_td[3]}]
set_property PACKAGE_PIN K4 [get_ports {ETH2_RGMII_rxc}]
set_property PACKAGE_PIN K3 [get_ports {ETH2_RGMII_rx_ctl}]
set_property PACKAGE_PIN M6 [get_ports {ETH2_RGMII_rd[0]}]
set_property PACKAGE_PIN L5 [get_ports {ETH2_RGMII_rd[1]}]
set_property PACKAGE_PIN P7 [get_ports {ETH2_RGMII_rd[2]}]
set_property PACKAGE_PIN P6 [get_ports {ETH2_RGMII_rd[3]}]

set_property PACKAGE_PIN Y8 [get_ports {ETH_MDIO_mdc}]
set_property PACKAGE_PIN W8 [get_ports {ETH_MDIO_mdio_io}]

set_property IOSTANDARD LVCMOS18 [get_ports {ETH2_RGMII_*}]
set_property IOSTANDARD LVCMOS18 [get_ports {ETH_MDIO_*}]

set_property PULLTYPE PULLUP [get_ports {ETH2_RGMII_*}]
set_property PULLTYPE PULLUP [get_ports {ETH_MDIO_*}]

#set_property slew FAST [get_ports {ETH2_RGMII_*}]
#set_property slew FAST [get_ports {ETH_MDIO_*}]

# Clock Period Constraints
create_clock -period 8.000 -name ETH2_RGMII_rxc -add [get_ports ETH2_RGMII_rxc]

## Use these constraints to modify output delay on RGMII signals if 2ns delay is
added by external PHY
#set_output_delay -clock [get_clocks ETH2_RGMII_txc] -max -1.0 [get_ports
{ETH2_RGMII_td[*]} ETH2_RGMII_txc]
#set_output_delay -clock [get_clocks ETH2_RGMII_txc] -min -2.6 [get_ports
{ETH2_RGMII_td[*]} ETH2_RGMII_txc] -add_delay
#set_output_delay -clock [get_clocks ETH2_RGMII_txc] -clock_fall -max -1.0 [get_ports
{ETH2_RGMII_td[*]} ETH2_RGMII_txc]
#set_output_delay -clock [get_clocks ETH2_RGMII_txc] -clock_fall -min -2.6 [get_ports
{ETH2_RGMII_td[*]} ETH2_RGMII_txc]

#clock setting
set_property UNAVAILABLE_DURING_CALIBRATION TRUE [get_ports ETH2_RGMII_td[1]]
set_property UNAVAILABLE_DURING_CALIBRATION TRUE [get_ports ETH_MDIO_mdio_io]

##clock setting
##set_property CLOCK_DEDICATED_ROUTE FALSE [get_nets zusys_i/gmii_to_rgmii_0/U0
/i_gmii_to_rgmii_block/rgmii_rxc_ibuf_i/0]
#set_property UNAVAILABLE_DURING_CALIBRATION TRUE [get_ports ETH2_RGMII_td[1]]

```

```

##False path constraints to async inputs coming directly to synchronizer
#set_false_path -to [get_pins -hier -filter {name =~ *idelayctrl_reset_gen
/*reset_sync*/PRE }]
#set_false_path -to [get_pins -of [get_cells -hier -filter { name =~ *i_MANAGEMENT
/SYNC_*/data_sync* }] -filter { name =~ *D }]
#set_false_path -to [get_pins -hier -filter {name =~ *reset_sync*/PRE }]

##False path constraints from Control Register outputs
#set_false_path -from [get_pins -hier -filter {name =~ *i_MANAGEMENT/DUPLEX_MODE_REG*
/C }]
#set_false_path -from [get_pins -hier -filter {name =~ *i_MANAGEMENT
/SPEED_SELECTION_REG*/C }]

## constraint valid if parameter C_EXTERNAL_CLOCK = 0
#set_case_analysis 0 [get_pins -hier -filter {name =~ *i_bufgmux_gmii_clk/CE0}]
#set_case_analysis 0 [get_pins -hier -filter {name =~ *i_bufgmux_gmii_clk/S0}]
#set_case_analysis 1 [get_pins -hier -filter {name =~ *i_bufgmux_gmii_clk/CE1}]
#set_case_analysis 1 [get_pins -hier -filter {name =~ *i_bufgmux_gmii_clk/S1}]

## constraint valid if parameter C_EXTERNAL_CLOCK = 0 and clock skew on TXC is
through MMCM
#set_case_analysis 0 [get_pins -hier -filter {name =~ *i_bufgmux_gmii_90_clk/CE0}]
#set_case_analysis 0 [get_pins -hier -filter {name =~ *i_bufgmux_gmii_90_clk/S0}]
#set_case_analysis 1 [get_pins -hier -filter {name =~ *i_bufgmux_gmii_90_clk/CE1}]
#set_case_analysis 1 [get_pins -hier -filter {name =~ *i_bufgmux_gmii_90_clk/S1}]

##These constraints are for non-Versal devices
##To Adjust GMII Rx Input Setup/Hold Timing
#set_property IDELAY_VALUE 16 [get_cells *delay_rgmii_rx_ctl]
#set_property IDELAY_VALUE 16 [get_cells -hier -filter {name =~ *delay_rgmii_rxd*}]
#set_property IODELAY_GROUP gpr1 [get_cells *delay_rgmii_rx_ctl]
#set_property IODELAY_GROUP gpr1 [get_cells -hier -filter {name =~ *delay_rgmii_rxd*}]
#set_property IODELAY_GROUP gpr1 [get_cells *idelayctrl]

#set_property slew FAST [get_ports [list {ETH2_RGMII_td[3]} {ETH2_RGMII_td[2]}
{ETH2_RGMII_td[1]} {ETH2_RGMII_td[0]} ETH2_RGMII_txc ETH2_RGMII_tx_ctl]]

#clock setting
#set_property CLOCK_DEDICATED_ROUTE FALSE [get_nets zusys_i/gmii_to_rgmii_0/U0
/i_gmii_to_rgmii_block/rgmii_rxc_ibuf_i/0]

```

Software Design - Vitis

For Vitis project creation, follow instructions from:

[Vitis](#)

Application

Template location: "<project folder>\sw_lib\sw_apps"

zynqmp_fsbl

TE modified 2021.2 FSBL

General:

- Modified Files: xfsbl_main.c, xfsbl_hooks.h/.c, xfsbl_board.h/.c (search for 'TE Mod' on source code)
- Add Files: te_xfsbl_hooks.h/.c (for hooks and board)
- General Changes:
 - Display FSBL Banner and Device Name

Module Specific:

- Add Files: all TE Files start with te_*
 - Si5338 Configuration
 - ETH+OTG Reset over MIO

zynqmp_fsbl_flash

TE modified 2021.2 FSBL

General:

- Modified Files: xfsbl_initialisation.c, xfsbl_hw.h, xfsbl_handoff.c, xfsbl_main.c
- General Changes:
 - Display FSBL Banner
 - Set FSBL Boot Mode to JTAG
 - Disable Memory initialisation

zynqmp_pmufw

Xilinx default PMU firmware.

hello_te0821

Hello TE0821 is a Xilinx Hello World example as endless loop instead of one console output.

u-boot

U-Boot.elf is generated with PetaLinux. Vitis is used to generate Boot.bin.

Software Design - PetaLinux

For PetaLinux installation and project creation, follow instructions from:

- [PetaLinux KICKstart](#)

Config

Start with **petalinux-config** or **petalinux-config --get-hw-description**

Changes:

- select SD default instead of eMMC:
 - CONFIG_SUBSYSTEM_PRIMARY_SD_PSU_SD_1_SELECT=y
- add new flash partition for bootscr and sizing
 - CONFIG_SUBSYSTEM_FLASH_PSU_QSPI_0_BANKLESS_PART0_SIZE=0x2000000
 - CONFIG_SUBSYSTEM_FLASH_PSU_QSPI_0_BANKLESS_PART2_SIZE=0x2000000
 - CONFIG_SUBSYSTEM_FLASH_PSU_QSPI_0_BANKLESS_PART3_NAME="bootscr"
 - CONFIG_SUBSYSTEM_FLASH_PSU_QSPI_0_BANKLESS_PART3_SIZE=0x80000

- select PSU_ethernet_2 instead of PSU_ethernet_3
 - CONFIG_SUBSYSTEM_ETHERNET_PSU_ETHERNET_2_SELECT=y

U-Boot

Start with **petalinux-config -c u-boot**

Changes:

- MAC from eeprom together with uboot and device tree settings:
 - CONFIG_ENV_OVERWRITE=y
- Boot Modes:
 - CONFIG_QSPI_BOOT=y
 - CONFIG_SD_BOOT=y
 - # CONFIG_ENV_IS_IN_NAND is not set
 - CONFIG_BOOT_SCRIPT_OFFSET=0x4040000

Change platform-top.h:

```
#include <configs/xilinx_zynqmp.h>
#no changes
```

Device Tree

project-spec/meta-user/recipes-bsp/device-tree/files/system-user.dtsi

```
/include/ "system-conf.dtsi"
#include <dt-bindings/gpio/gpio.h>
/ {
    chosen {
        xlnx,eeprom = &eeprom;
    };
};

/*----- QSPI ----- */
&qspi {
    #address-cells = <1>;
    #size-cells = <0>;
    status = "okay";
    flash0: flash@0 {
        //compatible = "flash name, "micron,m25p80";
        compatible = "jedec,spi-nor";
        reg = <0x0>;
        #address-cells = <1>;
        #size-cells = <1>;
    };
};

/*----- SD1 sd2.0 -----*/
&sdhci1 {
    disable-wp;
    no-1-8-v;
};

/*----- ETH PHY -----*/
/delete-node/ &psu_ethernet_2_mdio;
```

```

&gem2 {
    phy-handle = <&phyl_gem2>;
    phy-mode = "rgmii-id";
    status = "okay";

    reset-names = "ETH_RST";
    reset-gpios = <&gpio 78 GPIO_ACTIVE_LOW>;

    phyl_gem2: ethernet-phy@1 {
        device_type = "ethernet-phy";
        reg = <1>;
    };

    rgmii_0: rgmii_0@4 {
        phy-handle = <&phyl_gem2>;
        compatible = "xlnx,gmii-to-rgmii-1.0";
        reg = <4>;
    };
};

/*----- USB 2.0 only -----*/
&dwc3_0 {
    status = "okay";
    dr_mode = "host";
    maximum-speed = "high-speed";
    /delete-property/phy-names;
    /delete-property/phys;
    /delete-property/snps,usb3_lpm_capable;
    snps,dis_u2_susphy_quirk;
    snps,dis_u3_susphy_quirk;
};

&usb0 {
    status = "okay";
    /delete-property/ clocks;
    /delete-property/ clock-names;
    clocks = <0x3 0x20>;
    clock-names = "bus_clk";
};

/*----- I2C -----*/
&i2c0 {
    eeprom: eeprom@50 {
        compatible = "microchip,24aa025", "atmel,24c02";
        reg = <0x50>;
    };
};
};

```

Kernel

Start with `petalinux-config -c kernel`

Changes:

- Only needed to fix JTAG Debug issue:

- CONFIG_CPU_IDLE is not set
- CONFIG_CPU_FREQ is not set
- CONFIG_EDAC_CORTEX_ARM64=y

Rootfs

Start with **petalinux-config -c rootfs**

Changes:

- For web server app:
 - CONFIG_busybox-httpd=y
- For additional test tools only:
 - CONFIG_i2c-tools=y
 - CONFIG_packagegroup-petalinux-utils=y (util-linux,cpufrequtils,bridge-utils,mtd-utils,usbutils,pciutils,canutils,i2c-tools,smartmontools,e2fsprogs)

Applications

See "<project folder>\os\petalinux\project-spec\meta-user\recipes-apps"

startup

Script App to load init.sh from SD Card if available.

webfwu

Webserver application suitable for Zynq access. Need busybox-httpd

Additional Software

SI5338

File location "<project folder>\misc\PLL\Si5338_B\Si5338-*.slabtimeproj"

General documentation how you work with these project will be available on [Si5338](#)

Appx. A: Change History and Legal Notices

Document Change History

To get content of older revision got to "Change History" of this page and select older document revision number.

Date	Document Revision	Authors	Description
			<ul style="list-style-type: none"> • initial release

**Error
rendering
macro
'page-info'**

Ambiguous
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Document change history.

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Error rendering macro 'page-info'

Ambiguous method overloading for method `jdk.proxy241.$Proxy3496#hasContentLevelPermission`.
Cannot resolve which method to invoke for `[null, class java.lang.String, class com.atlassian.confluence.pages.Page]` due to overlapping prototypes between: `[interface com.atlassian.confluence.user.ConfluenceUser, class java.lang.String, class com.atlassian.confluence.core.ContentEntityObject]`
`[interface com.atlassian.user.User, class java.lang.String, class com.atlassian.confluence.core.ContentEntityObject]`